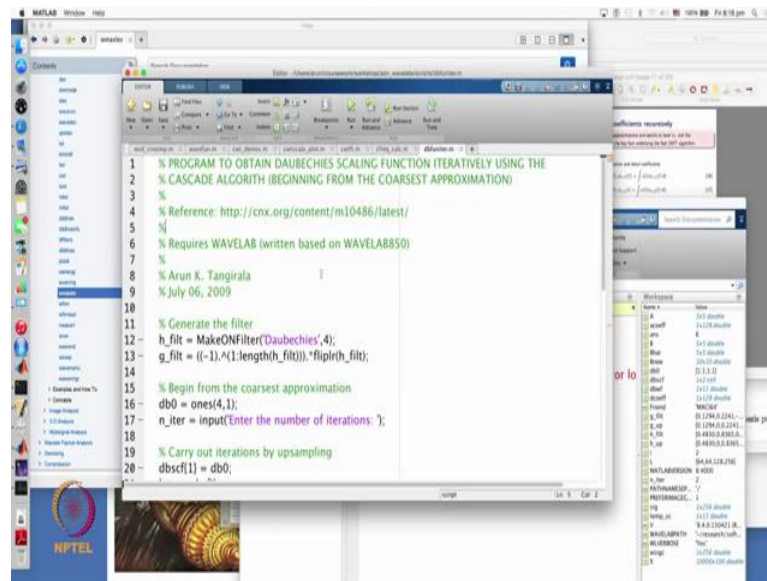


The script here... The script is shown here and you should be able to get the script from the web. When we post the lecture notes, we will also post the script. So, let me run the script and show you how the iterative algorithm works.

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The image shows a MATLAB script editor window with a script titled 'PROGRAM TO OBTAIN DAUBECHIES SCALING FUNCTION ITERATIVELY USING THE CASCADE ALGORITHM'. The script includes comments about the reference (http://cnx.org/content/m10486/latest/), the requirement for WAVELAB, and the author (Arun K. Tangirala, July 06, 2009). The script defines a function 'MakeONFilter' to generate the filter coefficients for the Daubechies family with a length of 4. It then initializes the filter coefficients and begins the iterative process by upsampling. The script is as follows:

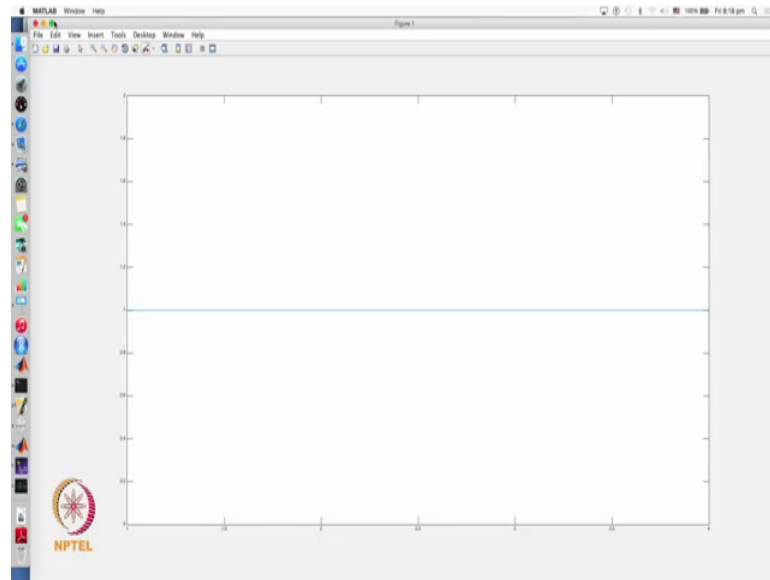
```
1 % PROGRAM TO OBTAIN DAUBECHIES SCALING FUNCTION ITERATIVELY USING THE
2 % CASCADE ALGORITHM (BEGINNING FROM THE COARSEST APPROXIMATION)
3 %
4 % Reference: http://cnx.org/content/m10486/latest/
5 %
6 % Requires WAVELAB (written based on WAVELAB850)
7 %
8 % Arun K. Tangirala
9 % July 06, 2009
10
11 % Generate the filter
12 h_filt = MakeONFilter('Daubechies',4);
13 g_filt = (1-1).^(1:length(h_filt)).*flip(h_filt);
14
15 % Begin from the coarsest approximation
16 db0 = ones(4,1);
17 n_iter = input('Enter the number of iterations: ');
18
19 % Carry out iterations by upsampling
20 dbscf(1) = db0;
```

So, what I am doing here is, I am actually using wave lab to get the low-pass filter coefficients. I can use the wavelet tool box as well, does not matter. And, what I am interested in here is generating the Daubechies wavelet of vanishing moments too. In fact, if you look at the line here, it says that... It is asking for the filter coefficients corresponding to Daubechies family with the number 4 here. This number is not the vanishing moment, but the length of the filter. That is why I said there are conventions where people use the length as the specification or half the length which is a vanishing moment as a specification. Here in wavelab, the MakeONFilter; ON means orthonormal. That routine requires you to specify the length rather than the vanishing moments. So, I am asking for the filter coefficients here. And, I am interested in generating the ϕ of t corresponding to this db2. And, the accuracy of ϕ of t depends on how many times you run through that algorithm that we just discussed.

How do we initialize the ϕ of t ? One thing I know for sure that, ϕ of t cannot have a zero average because it is a low-pass filter. So, what I am going to do is I am going to initialize the ϕ of t as a bunch of 1's – just a vector of 1's. In fact, ideally, I should be initializing such that it is not 1's, but $1/n$ – $1/4$, so that the sum of it. In fact, the area under that of ϕ of t should come out to be 1 and so on. But, we will not do that; that normalization we will do later on. So, as you can see here, my initial guess is that,

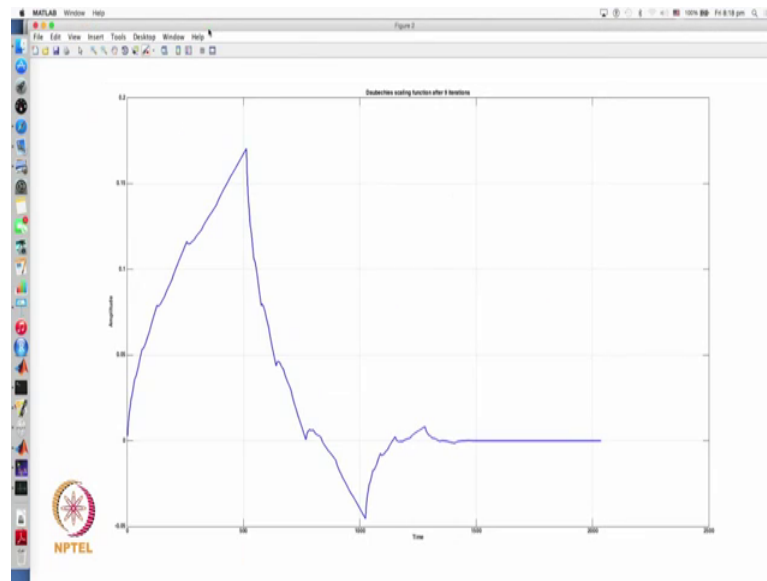
ϕ of t is taking on a value of one over a certain interval. So, this is how the initial one looks like.

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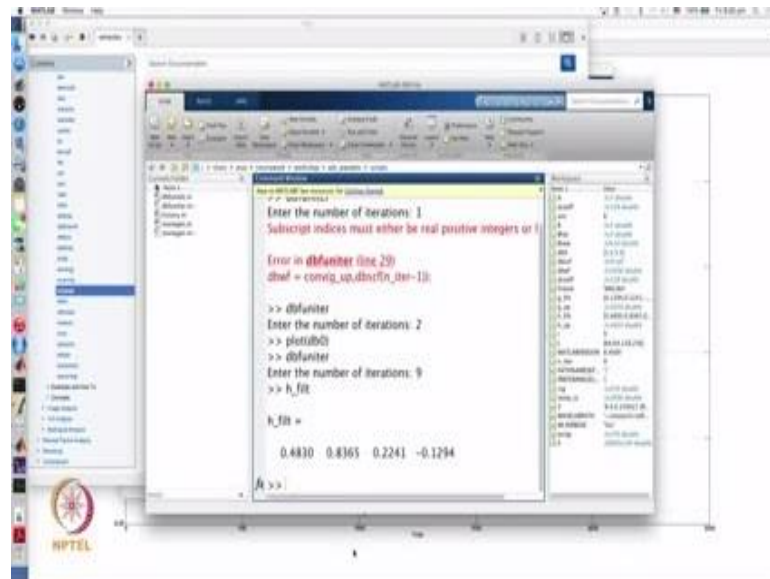
Let me show you the initial Daubechies wavelet – initial guess of the Daubechies wavelet, is just a plane straight line; that is it. Obviously, I know this is not db 2. But, the iterative algorithm magically constructs the db 2. Let us quickly see how it looks like. When I run through the iterations, I will take you... Let me run this here and then I will take you through the animation.

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So, suppose I run it for about 9 iterations, what I have with me here are the Daubechies scaling function. Look at how it magically constructed the Daubechies wavelet from a guess. But, that guess is very important; you have to give a guess that make sense. You cannot give a guess such that it has a zero average; that is all. So, as long as you give a ϕ of t that has non-zero average, it should work fine. And, of course, here what you see on the x-axis; it says time. But, it is not time really; it is a number of iterate points over which I have computed iteratively. I started off with four points; but, with every iteration, it is doubled; the number of points is doubled. The time interval over which it exists is actually 0 to 3. Why? Because db 2 has four filter coefficients. Therefore, its support is over n_1 comma n_2 ; 0; n_1 is 0; n_2 is 3; that is, I have four filter coefficients at n equals 0, 1, 2, 3.

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```
Enter the number of iterations: 1
Subscript indices must either be real positive integers or logicals.

Error in dftfilter (line 29)
    dhat = convg_up.dhcat(n_iter-1);

>> dftfilter
Enter the number of iterations: 2
>> plot(dhat)
>> dftfilter
Enter the number of iterations: 9
>> h_fit

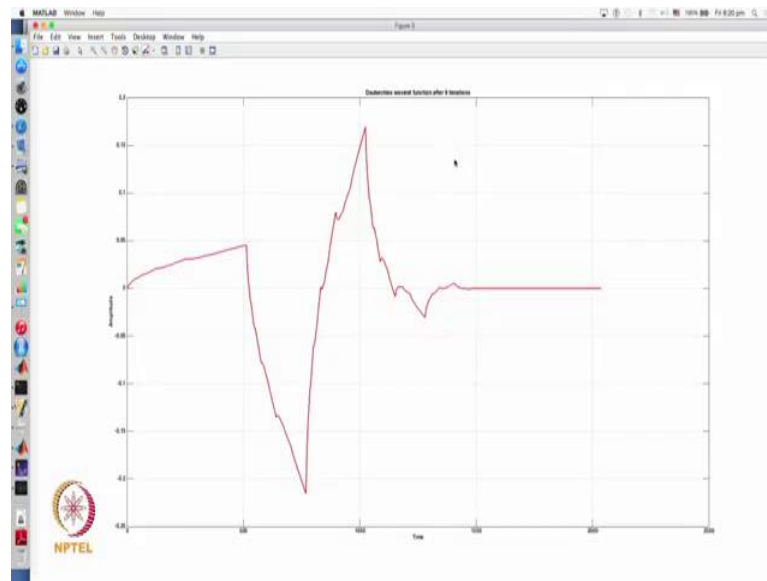
h_fit =

    0.4830    0.8365    0.2241   -0.1294

h>>
```

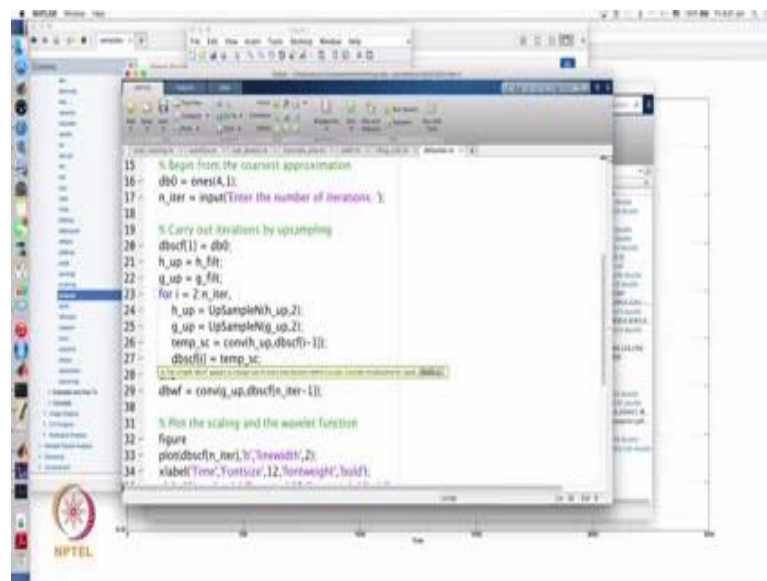
And, what are those filter coefficients? Those filter coefficients are here. You can also obtain these filter coefficients from matlab's wavelet tool box. There are four filter coefficients at n equal to 0, 1, 2, 3. So, the support of h is over 0 comma 3. By the result that we are seen earlier, support of ϕ is also over 0 comma 3. What you see as a plot here is actually over 0 comma 3. So, the time... This is only the number of points from 0 to 3. All right.

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And, the associated wavelet has also been constructed. The moment I have the scaling function, I can also run the same algorithm by starting off with the guess for the wavelet. And, this is how the wavelet is built.

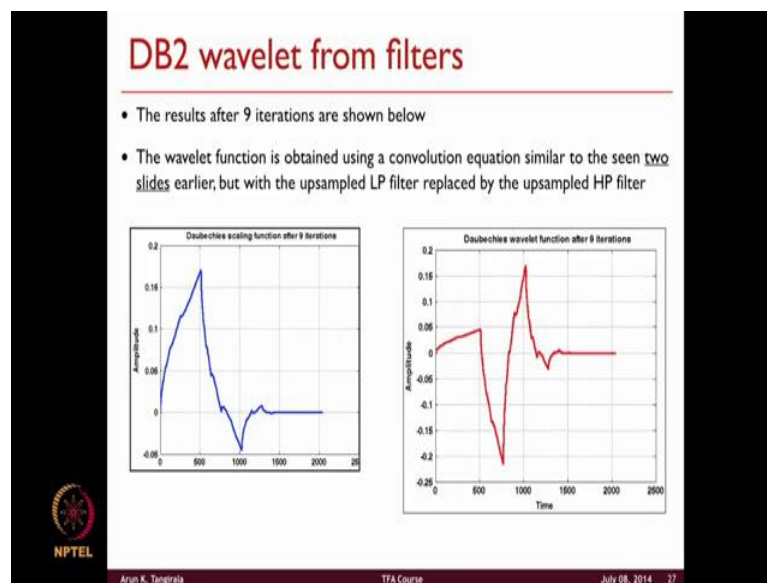
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So, if you look at the code, the way I have written is... This is the wavelet function. And,

all I do is... Remember the wavelet at any stage is a convolution of g with the scaling function, because that is from the scaling relation. The ψ of t is integral g of n ϕ of t minus n ; $\sum g$ of n ϕ of t minus n ; that is it. So, I use that convolution expression and compute the wavelet. I do not have to run another iterative algorithm at all. All I need to do is generate ϕ of t and I will get ψ of t . So, I hope you understand what is being done here. Essentially, this is a scaling relation that we have seen earlier.

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So, let me also show you just to make the thing very effective; that is, for you to see gradual guess – refinement of ϕ of t across the iterations, I am going to take you to another presentation that I have from previous workshop; where, this is the initial guess. Second guess – this is the development in fact after three iterations. And then, gradually, it develops fourth iteration, fifth iteration, sixth, seventh, eighth; that is it. So, then, you have a wavelet. So, that is called... That is the iterative algorithm.

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Lecture 8.4 References

Designing a wavelet

A wavelet is designed by requiring that $\phi(t)$ be orthonormal and has LP filter characteristics and by specifying (i) the number of vanishing moments and (ii) orthogonality / bi-orthogonality requirements.

Daubechies filter with $N = 2$

1. Low-pass filter characteristics: $\sum_{n=0}^{2N-1} h[n] = \sqrt{2}$
2. Orthonormality of $\phi(t)$: $\sum_{n=0}^{2N-1} h[n]h[n+2k] = \delta[k], k = 0, 1, \dots, N-1.$
3. Vanishing moments: $\sum_{n=0}^{2N-1} (-1)^n n^k h[n] = 0, k = 0, 1, \dots, N-1$

Results in $(2N+1)$ linearly dependent equations for $2N$ unknowns. We can exclude one of these equations to arrive at a unique solution for the filter coefficients.

For orthogonal wavelets, synthesizing wavelet are identical to the analyzing wavelets for perfect reconstruction.

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Now, as I said earlier, there is also a second algorithm.

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Lecture 8.4 References

Cascade algorithm for constructing $\phi(t)$ and $\psi(t)$

The cascade algorithm works backwards using the reconstruction equation and the following fact:

$$\langle \phi(t), \phi_{0,p} \rangle = 1, p = 0 \text{ and is zero } \forall p \neq 0.$$

$$\langle \psi(t), \phi_{0,p} \rangle = 0, \forall p \neq 0.$$

Cascade algorithm

1. Choose the associated low-pass filter $h[n]$.
2. Start with a single coefficient of unity. Set all the details to zero (at all scales).
3. Apply the reconstruction algorithm iteratively until a desired level is reached (as dictated by the user-specified iteration).

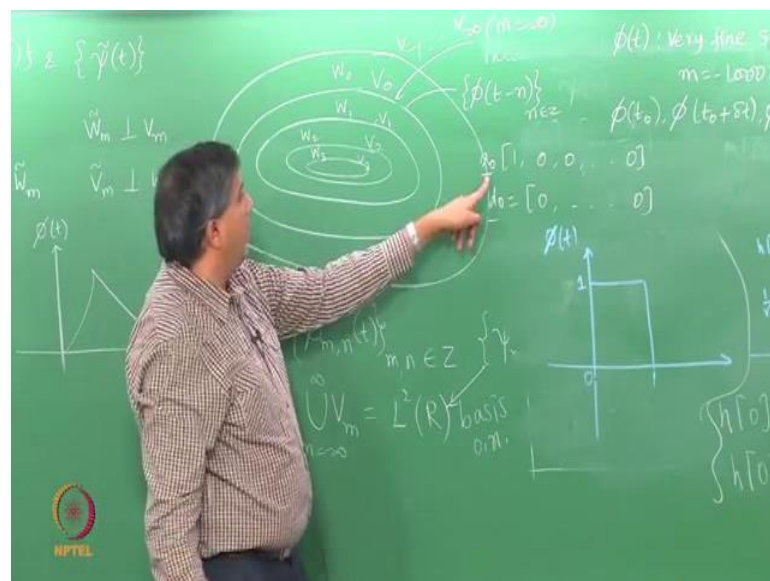
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That is known as the cascade algorithm, which has a very beautiful thing to it. It is a very nice way of reconstructing $\phi(t)$; it is very elegant. This algorithm works backwards using the reconstruction equation and the following fact. Now, remember that, in the

MRA, what I am doing is I am constructing approximations of signals that are of finite energy. What I do here is I set the signal as a scaling function itself. Why not? See even a scaling function is some signal. Now, when I set the signal as a scaling function itself, then I know by the orthonormality property that, the inner product between the scaling function and the scaled scaling function is one. Here I am right now I am looking at scale 1, that is, at m equals 0. As you can see from the subscript here; and, p here refers to the translate. So, the inner product between ϕ of t , which is the scaling function – the continuous one and the ϕ of 0 comma p , that is, its own translate in other words. So, it is other way of saying that, the ϕ of t is orthonormal; that is all I am using. That is a property that I am using. But, I am rewriting it as an inner product.

And, I also used the property that, the ϕ and ψ are orthonormal at any scale. And, here I am choosing zero scale. But, if you look at this result from an approximation coefficient view point; now, think carefully; I start from the signal, which is ϕ of t and I start projecting it onto different subspaces V_0 or V minus 1 or V minus 2 and so on. Ideally, where does ϕ of t live? ϕ of t lives in the finest scale; it lives at V minus infinity; ϕ of t lives in V minus infinity; that is, when m goes to infinity, that is where ϕ of t is residing. You can project this ϕ of t onto any of the subspaces. Let me just show that to you on the graph.

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So, what is happening here is as I go here, I get v minus infinity, which is corresponding to m equals infinity. So, when I have ϕ of t ... ϕ of t resides in this space really; v of minus infinity is actually the finest scale. I can project that let us say to v_0 , which will construct some approximation, because v_0 – what is it spanned by? v_0 is spanned by ϕ of t minus n ; and, n belonging to the interior side. And, what that result says is whenever I project ϕ of t onto v naught, there is only going to be one approximation coefficient that is unity and all the other approximation coefficients are going to be 0. So, imagine instead of assuming v minus infinity, I have ϕ of t at a very fine scale. Let us say at very very fine scale, maybe m equals... In fact, this is not m equals minus infinity; m is minus infinity. So, let us say I have over very fine scale, m equals minus 1000. What does m equals minus 1000 mean? A very fine scale over a very fine grid. So, ϕ of t is also known over a very fine grid. So, we will just relax that it is continuous; rather imagine that, ϕ of t is now known over an extremely fine grid.

When I come from an extremely fine grid to v_0 , what I would have generated is a bunch of approximation coefficient; it is like taking any signal and I decompose any signal to some level; I have a number of coefficients. That signal is also sampled signal. The number of approximation coefficients of course will be much lesser than the original signal. So, here also what I am doing is I am taking ϕ of t known at some very fine grid. Let us say t naught and then t naught plus Δt ; ϕ at t naught $2 \Delta t$ and so on. So, a very fine grid and projecting it. Here I have a bunch of approximation coefficients. Those approximation coefficients will be of certain length. And, what that result says is when I feed; when I perform a decomposition of ϕ of t to a level 0 let us say; then, what happens? I have a bunch of approximation coefficients, which look like 1; and, rest of them are all 0's. The length of this of course, is determined by what length you are looking at.

In fact, if you have some n grid points here... Let me not confused with this m here. Let us say I have s grid points here. Then, by the time I come to 0, the number of coefficients here would be s over $2^m - 2^{1000}$ if that is at 1000. But, that does not matter. Essentially, this ϕ is known at some very fine scale over a grid and I have subjected that to an approximation or a decomposition, where this result says you start from the finest scale and perform a decomposition; you will always end up with these set

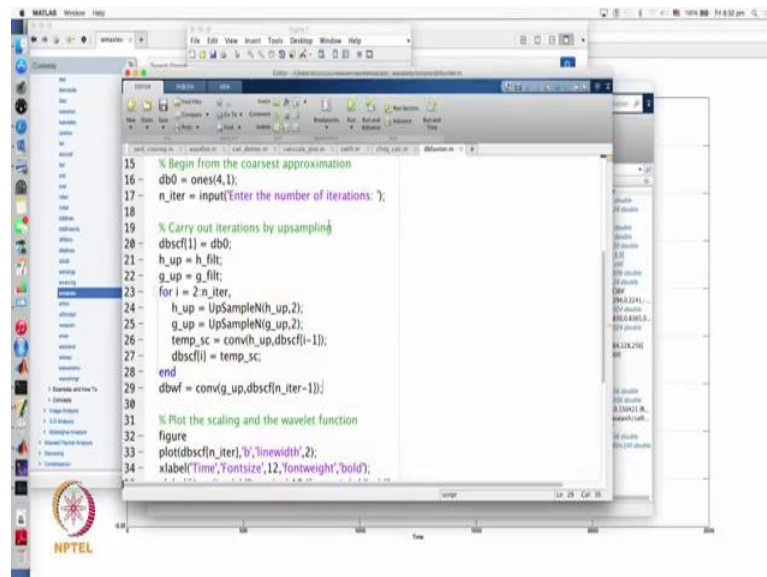
of approximation coefficients. And also, the detailed coefficients at this scale would be all 0's because the ϕ is orthonormal to the wavelet; which means the low-pass filter is orthonormal to the high-pass filter. Therefore, there are no high frequency coefficients at all.

Now, I do not know what is that ϕ of t ; but I know for sure that, any ϕ of t associated with the low-pass filter will produce this approximation and detailed coefficient at level 0. Now, I reconstruct. So, I would like to go from v_0 to v_{-1} . So, this here is the projection of ϕ of t onto a naught. I am going to now reconstruct a minus 1. I can do that; I have the reconstruction algorithm. So, I am going to run a naught through the reconstruction algorithm repeatedly as many times as I want to get ϕ of t . That is a basic idea behind the cascade algorithm; it is very simple one. But, you... And, uses the orthonormality property. So, what you do is you choose the associated low-pass filter whatever... For whatever family you want to construct the scaling function, start the low-pass filter, because it is all about constructing ϕ of t from the low-pass filter and then get your... Set initialize your guess for the... Not guess, initialize your approximation coefficients at level 0. Does not have to be level 0; but, just for discussion sake, we say it is level 0.

And then, set all the details to 0 and apply the reconstruction algorithm repeatedly. And, how do you do that? There is a command called `upcoef` in wavelet tool box of matlab, which will allow you to reconstruct repeatedly either from the approximation coefficients or the detailed coefficients. And then, you will be able to reconstruct it at any level. All right? That is nothing but the reconstruction algorithm with all the other band coefficients set to 0; that is all; it is nothing very great about it. In fact, this algorithm now can be applied to the wavelet also. For the wavelet, what happens is... The property of the wavelet is such that the detailed coefficients... If you were to feed not the scaling function as a signal; but, if you were to feed the wavelet as a signal, what kind of approximation and detailed coefficients would you get? You would get the reverse situation. So, I start from ψ of t . That is what I would feed and then perform the decomposition many many many times. Then, when I come to a very coarse scale, what I would have is all zero approximation coefficients, because a wavelet has nothing in the low frequency band. And, the detailed coefficients would be 1 at lag 0; that is, at time 0

and 0 elsewhere, because of the orthonormality property of the ψ ; and, that is it. So, I can also apply this to generate the wavelet. And, this is exactly the algorithm that is implemented in the wavefun.

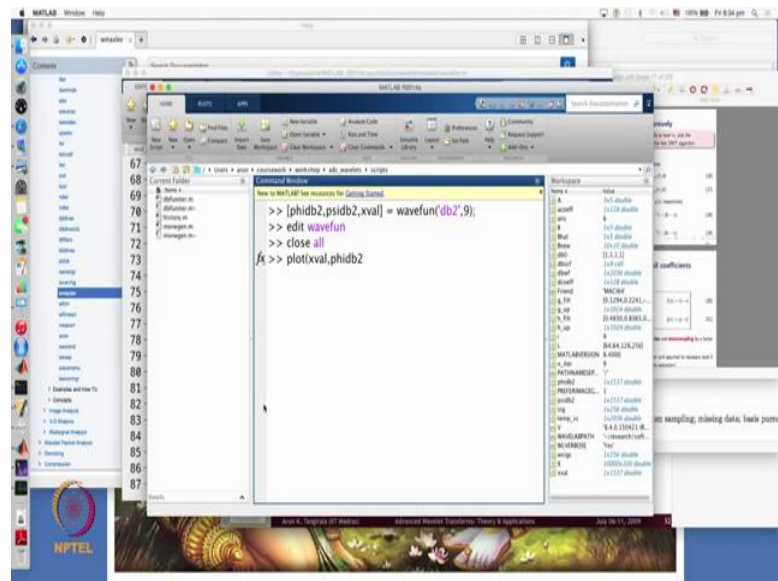
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A screenshot of a MATLAB script editor window. The script defines a function 'wavefun' that generates Daubechies wavelet functions. It starts with a comment '% Begin from the coarsest approximation' and initializes 'db0 = ones(4,1)'. It then takes an input 'n_iter' for the number of iterations. The script uses a loop to iteratively calculate the scaling function 'dbwf' and the wavelet function 'dbscf' by upsampling and filtering. Finally, it plots the scaling function and the wavelet function using 'figure' and 'plot' commands. The script is as follows:

```
15 % Begin from the coarsest approximation
16 db0 = ones(4,1);
17 n_iter = input('Enter the number of iterations: ');
18
19 % Carry out iterations by upsampling
20 dbscf(1) = db0;
21 h_up = h_filt;
22 g_up = g_filt;
23 for i = 2:n_iter
24     h_up = UpSampleN(h_up,2);
25     g_up = UpSampleN(g_up,2);
26     temp_sc = conv(h_up,dbscf(i-1));
27     dbscf(i) = temp_sc;
28 end
29 dbwf = conv(g_up,dbscf(n_iter-1));
30
31 % Plot the scaling and the wavelet function
32 figure
33 plot(dbscf(n_iter),'b','linewidth',2);
34 xlabel('Time','FontSize',12,'Fontweight','bold');
```

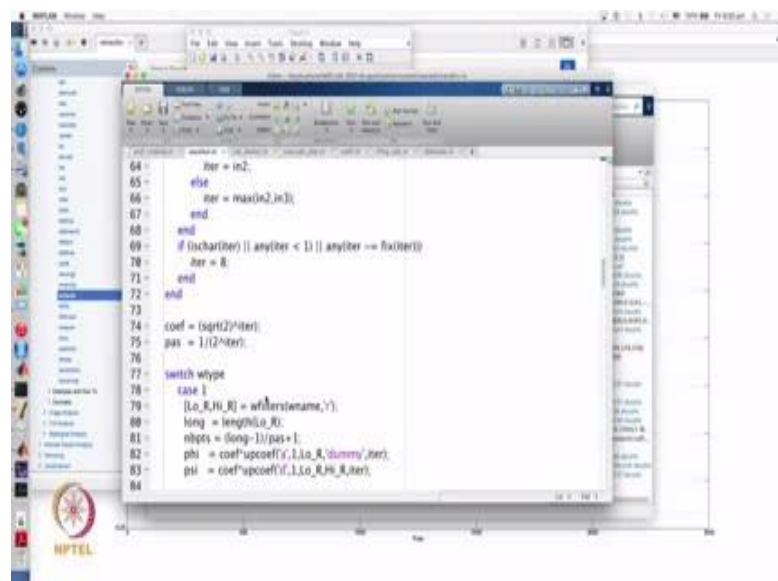
So, remember; we use this wavefun long ago in the CWT – lecture 7.2. When we talked about scaled frequency, we started with a specification of the low-pass and high-pass filters for the Daubechies. And then, we said... We specified the number of iterations to generate the scaling function and the wavelet. And, that is exactly what the wavefun does.

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So, let me do that; phi db; you can see here I am going to 12 or even 9 iterations; does not matter. And, that gets me the db 2. In fact, if you open up wavefun, you will see that, it is exactly implementing the algorithm that we just discussed.

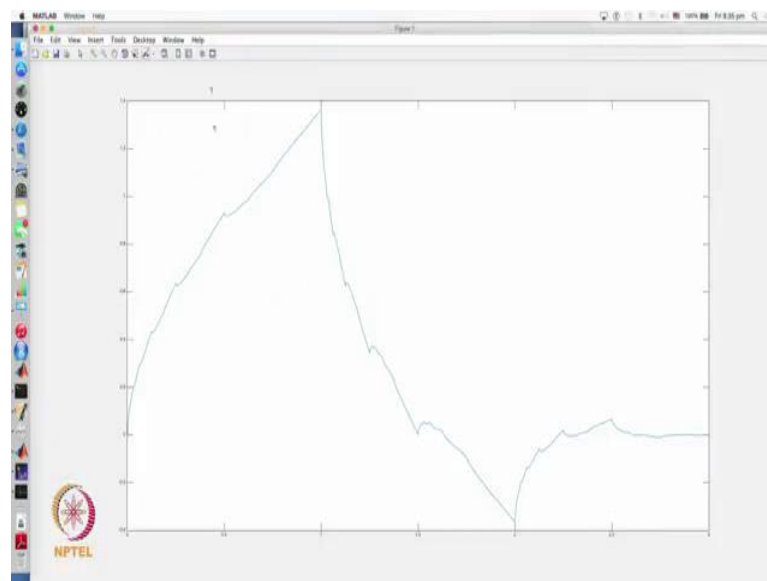
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If you throw away all of this, what it does is here. Here it gets a filter coefficients and the

up c o e f is a key. To generate the scaling function, it uses an approximation coefficients. And, what are the approximation coefficients? If you go up, you will see... In fact, here itself, it says, the approximation coefficient is simply a single coefficient of value 1; that is, you have started from ϕ of t and you have decomposed it to such a level that, only a single coefficient is available; and, that single coefficient value is 1. Given any signal, I can perform the maximum decomposition such that I only have one coefficient left. And, if I... What the previous discussion tells us is if I start from the scaling function itself, that is, a decomposition scaling function itself, there will come a level at which there is a single approximation coefficient. And, that is the value of 1. Likewise, if I start from the wavelet and I perform the decomposition, then I can reach a level at which there is a single detailed coefficient; and, that is the value 1. So, the up c o e f performs a repeated reconstruction; that is at the core of wavefun. So, let us plot here.

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So, as you can see, this is this scaling function now over the interval 0 to 3. As you can see, it is over 0 to 3 because that is the effective support. And, the result of course, looks identical at least in shape to what we had with the previous algorithm. And, if I look at the wavelet, this is how you iteratively generate the scaling functions and wavelets starting from filters.

Now, what we shall do in the next matlab session – the fresh matlab session is I am going to show you how to compute the wavelet transforms and how one can perform signal compression and how one can perform signal estimation and all of that. Primarily, it will be a matlab session; and, I will give you a brief theory of signal estimation. The basic idea and signal estimation has already been discussed. You decompose the signal and then you apply some criterion like we did on the CWT and the short-time fourier spectrogram and so on. You apply a criterion on the coefficients at all the scales or at some scales and so on. We call this as thresholding; that is, you throw away certain coefficients or you retain and so on, and then reconstruct. So, the basic idea is transform, perform some operation in the transformed domain, and then reconstruct. That operation in wavelet domain is nothing but thresholding. So, there are several flavors of thresholding and of this of this basic idea, which we will discuss in the next matlab session. So, it will be more practice-oriented and a bit of theory on signal estimation. That would be the final lecture on this topic of discrete wavelet transforms.

There are of course, other applications of dwt such as discontinuity detection. I will also briefly illustrate the idea of discontinuity detection in DWT; and, how choosing wavelets with higher vanishing moments – different vanishing moments makes a difference in discontinuity detection. So, what we are going to do is look at how to perform decomposition and reconstruction, detect discontinuity briefly, and then a spend lot more time on signal estimation, discuss the different thresholing methods. And, with that, we will conclude the topic of the discrete wavelet transforms. And finally, we will have a closing session, that is, a closing lecture for the entire course. Hopefully, you enjoyed this lecture and learnt quite a bit. And, see you in next matlab session.