

Advanced Mathematical Techniques in Chemical Engineering
Prof. S. De
Department of Chemical Engineering

Indian Institute of Technology, Kharagpur
Module No. # 01
Lecture No. # 34
Solution of non-homogeneous Parabolic PDE

Good afternoon, everyone! So, we are starting this class with the solution of non-homogeneous partial differential equation using the Green's function method. In the earlier class we have developed the theory of Green's function method, and we looked into several steps of a solution. First, we construct the causal Green's function, then we will be looking into the adjoint Green's function, then we connect the adjoint Green's function with the original problem.

Now, we develop the various methods, how to obtain the Green's function depending on the source of the point where we are applying the unit impulse or unit step function, and we will be having a lower half solution and the upper half solution; and we have seen several conditions which will be coming out, for example, continuity of Green's function, jump discontinuity condition and the actual boundary conditions prevalent at that two boundaries, so, we will be having four constants, and four conditions to evaluate these four constants.

So, we are able to completely define the Green's function. Once we defined the Green's function, then we looked into, took up an actual problem in ordinary differential equation and demonstrated our method, how to utilize this method, how to solve this problem with the Green's function method.

Next we took up another problem, which was basically an ordinary differential equation; there is non-homogeneity in the governing equation as well as the non-homogeneity in the boundary condition.

Again, we solve that problem almost completely by using Green's function method, to demonstrate our Green's function method in order solve the ordinary differential equation.

However, the Green's function method need not to be used for the solution of ordinary differential equation which are non-homogenous, there are more elegant and direct methods available, but we have just taken these methods these examples in order to demonstrate. Now, these methods become very useful and handy whenever we will be moving into the partial differential equations.

So, first example I will be talking about, I will be talking about a parabolic partial differential equation which is non-homogeneous in nature, and these equations are quite common in chemical engineering applications because they represent a transient state.

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Parabolic non-homogeneous PDE

$$\frac{\partial u}{\partial t} = \frac{\partial^2 u}{\partial x^2} + f(x,t)$$

$$\frac{\partial u}{\partial t} - \frac{\partial^2 u}{\partial x^2} = f(x,t) \quad | \quad Lu = f$$

$$L = \frac{\partial}{\partial t} - \frac{\partial^2}{\partial x^2}$$

at $t=0$, $u=h$ ✓
 at $x=0$, $u=p$ ✓
 at $x=1$, $u=q$ ✓

So, we will formulate this problem, go through the theory develop it and try to solve this problem completely. So, the governing equation of this problem is, $\frac{\partial u}{\partial t}$ is equal to $\frac{\partial^2 u}{\partial x^2}$ plus some non-homogeneous term, which is a function of x and t both; so, $\frac{\partial u}{\partial t} - \frac{\partial^2 u}{\partial x^2}$ is equal to f of x and t , so, this is in the form of Lu is equal to f , where the operator L is $\frac{\partial}{\partial t} - \frac{\partial^2}{\partial x^2}$.

On the other hand, the boundary conditions and initial conditions defined at t is equal to 0, u equal to h - it may be a function of x or it may be a constant; at x is equal to 0, u is equal to p ; at x is equal to 1, let us say, u is equal to q .

So, we consider the problem completely, non-homogeneous, non homogeneity at the governing equation, non-homogeneity at the boundary conditions as well. So, there are four sources of non-homogeneity in this problem.

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Construction of Causal Green's function

$$\frac{\partial g(x,t|x_0,t_0)}{\partial t} - \frac{\partial^2 g(x,t|x_0,t_0)}{\partial x^2} = \delta(x-x_0)\delta(t-t_0)$$

Subj to: at $t=0$, $g=0$
at $x=0$ and $x=1$, $g=0$

Use partial Eigenfunction method.

$$g(x,t|x_0,t_0) = \sum_{n=1}^{\infty} \underline{a_n(t)} \underline{\phi_n(x)}$$

So, if you remember, the first step construction of causal Green's function, so, we do that construction of causal Green's function...So, what is the construction? So it is a two-dimensional problem; so, we used to have a unit impulse at the location x naught t naught that is number one.

Secondly, the unit impulse, the non-homogeneous term in the governing equation must be replaced by the unit impulse. So, therefore, the construction is $\frac{\partial g(x,t|x_0,t_0)}{\partial t} - \frac{\partial^2 g(x,t|x_0,t_0)}{\partial x^2} = \delta(x-x_0)\delta(t-t_0)$.

And we forced all the boundary conditions of the original problem to be homogeneous. So, that was the condition of formulation of Green's function- at t equal to 0 my g is equal to 0; at x is equal to 0; and at x is equal to 1 our g is equal to 0.

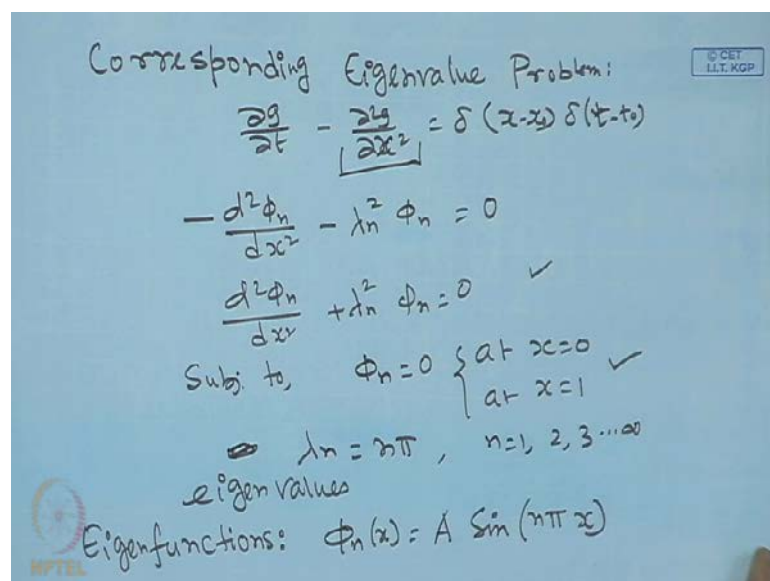
Since we had initial conditions as Dirichlet, boundary conditions as Dirichlet boundary conditions, but non-homogeneous in the original problem, the boundary conditions are made to be homogeneous- the initial condition was non-homogeneous, so it has to be made homogeneous as well.

Now, what we do? We use partial Eigenfunction method to solve this problem. What is the partial Eigenfunction method?

The partial Eigenfunction method is that, the solution, that means g , the solution, g , is supposed to be it is, it is a function of a standard Eigenvalue problem, because this boundary conditions are homogeneous, so, this function can be expressed as a linear combination of eigenfunctions that is present in the corresponding eigenvalue problem. So, therefore, $g(x, t) = \sum_{n=1}^{\infty} \phi_n(x) g_n(t)$ is a function of n , which is a function of time, and ϕ_n which will be function of space; so, n is equal to 1 to infinity, this is called an Eigenfunction method.

So, what a ϕ_n are? ϕ_n are the eigenfunction corresponding to the eigenvalue problem. And what are the corresponding coefficients? The corresponding coefficients are basically some kind of coefficients which are a function of time, then only g will be function of x and time.

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Corresponding Eigenvalue Problem:

$$\frac{\partial g}{\partial t} - \frac{\partial^2 g}{\partial x^2} = \delta(x-x_0)\delta(t-t_0)$$

$$-\frac{d^2 \phi_n}{dx^2} - \lambda_n^2 \phi_n = 0$$

$$\frac{d^2 \phi_n}{dx^2} + \lambda_n^2 \phi_n = 0 \quad \checkmark$$

Subj. to, $\phi_n = 0 \quad \left\{ \begin{array}{l} \text{at } x=0 \\ \text{at } x=1 \end{array} \right. \quad \checkmark$

$\Rightarrow \lambda_n = n\pi, \quad n=1, 2, 3, \dots, \infty$

Eigenvalues

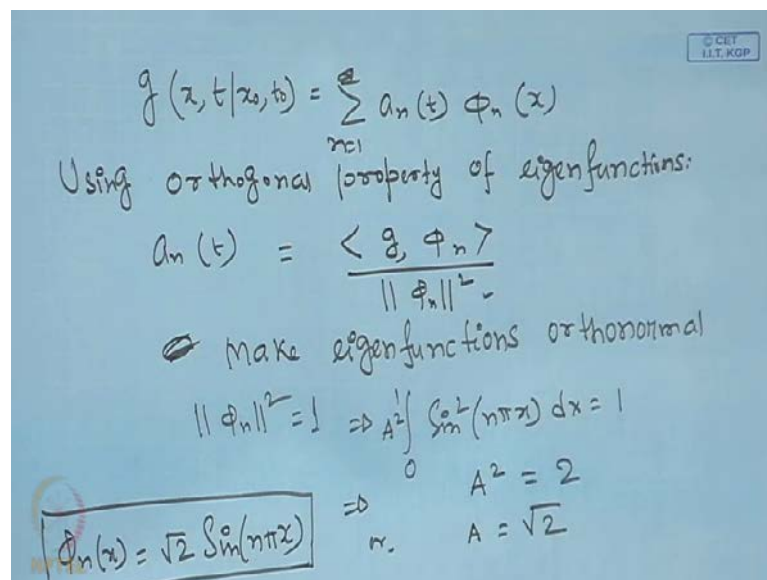
Eigenfunctions: $\phi_n(x) = A \sin(n\pi x)$

So, let us formulate the corresponding eigenvalue problem. So, corresponding eigenvalue problem now becomes, if you look into the governing equation $\frac{\partial g}{\partial t} - \frac{\partial^2 g}{\partial x^2} = \delta(x-x_0)\delta(t-t_0)$ is equal to $\delta(x-x_0)\delta(t-t_0)$; so, if you look into the space boundary conditions in space, it has 2 boundary conditions and these two boundary conditions are homogeneous, so, this corresponding eigenvalue problem is nothing but $-\frac{d^2 \phi_n}{dx^2} - \lambda_n^2 \phi_n = 0$.

So, this is the corresponding eigenvalue problem; so, $\frac{d^2 \phi_n}{dx^2} + \lambda_n \phi_n = 0$, and the boundary conditions must be satisfied by the boundary condition of the original problem; the original problem is basically a g problem- if you look into the boundary conditions of g, both the boundary conditions are homogeneous. Therefore, we have $\phi_n = 0$ both at $x = 0$ and at $x = 1$.

So, we know the solution of this problem, the eigenvalues are $n\pi$ - so, these are the eigenvalues n is equal to 1, 2, 3 up to infinity; and eigenfunctions are sin functions- so these eigenfunctions are $\sin n\pi x$.

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Handwritten mathematical derivation on a blue background:

$$g(x, t | x_0, t_0) = \sum_{n=1}^{\infty} a_n(t) \phi_n(x)$$

Using orthogonal property of eigenfunctions:

$$a_n(t) = \frac{\langle g, \phi_n \rangle}{\|\phi_n\|^2}$$

Make eigenfunctions orthonormal

$$\|\phi_n\|^2 = 1 \Rightarrow A^2 \int_0^1 \sin^2(n\pi x) dx = 1$$

$$\Rightarrow A^2 = 2$$

$$A = \sqrt{2}$$

Final result boxed: $\phi_n(x) = \sqrt{2} \sin(n\pi x)$

Therefore, if we look into the solution of g, which is constructed by partial eigenfunction expansion method, this will be nothing but $\sum_{n=1}^{\infty} a_n(t) \phi_n(x)$. So, we know that eigenfunctions are orthogonal to each other, so, using orthogonal property of the eigenfunctions, we can evaluate the constant a_n ; a_n will be nothing but inner product of g and ϕ_n divided by norm of ϕ_n square.

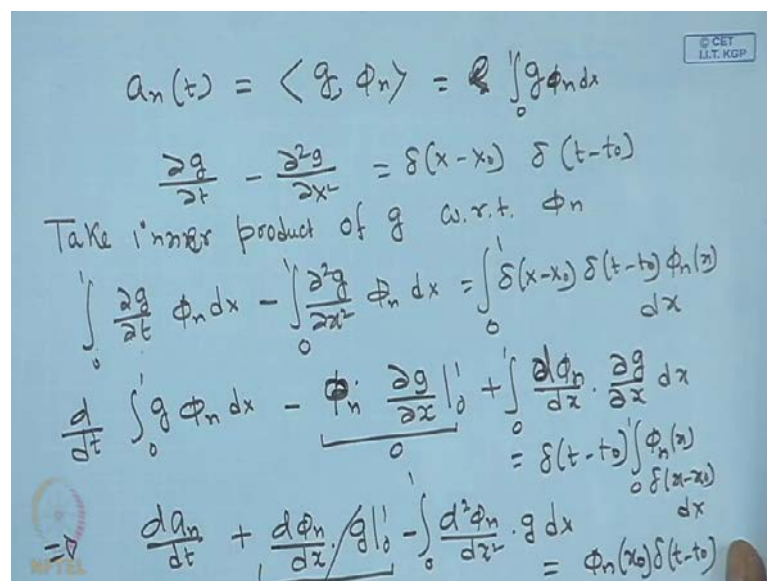
So, that means what we have done here: we multiply both side by $\phi_m(x)$ and integrate over the domain of x; in the right hand side, if you open up the summation series, you will be getting only one term that will be surviving, that will be ϕ_n - when n is equal to m all the other terms will vanish because of the orthogonal property of the eigenfunctions sin functions. So, you will be getting a_n into ϕ_n norm of ϕ_n on the

right hand side and then you will be getting on the left hand side integration of $g \phi_n dx$, so, it will be inner product of g and ϕ_n .

Now, what we do? We make the eigenfunctions orthonormal. So, we make eigenfunctions orthonormal. So, norm of ϕ_n square should be equal to 1, so, integral from 0 to 1 of $\sin^2 n\pi x$ – so, there will be a square is there, it is constant, so it will be taken out of the integral sign- $\sin^2 n\pi x$ dx is equal to 1 makes it orthonormal.

Now, integral $\sin^2 n\pi x$ dx is half, that we have already proved earlier, so, a square is equal to 2 or a is equal to root 2. So, therefore, the eigenfunctions are $\phi_n x$ is equal to root over 2 $\sin n\pi x$. If we formulate the eigenfunctions like this, then the eigenfunctions ϕ_n becomes orthonormal, and the denominator of this equation will be is equal to 1.

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Handwritten mathematical derivation on a blue background:

$$a_n(t) = \langle g, \phi_n \rangle = \int_0^1 g \phi_n dx$$

$$\frac{\partial g}{\partial t} - \frac{\partial^2 g}{\partial x^2} = \delta(x-x_0) \delta(t-t_0)$$

Take inner product of g w.r.t. ϕ_n

$$\int_0^1 \frac{\partial g}{\partial t} \phi_n dx - \int_0^1 \frac{\partial^2 g}{\partial x^2} \phi_n dx = \int_0^1 \delta(x-x_0) \delta(t-t_0) \phi_n(x) dx$$

$$\frac{d}{dt} \int_0^1 g \phi_n dx - \left[\phi_n \frac{\partial g}{\partial x} \right]_0^1 + \int_0^1 \frac{\partial \phi_n}{\partial x} \frac{\partial g}{\partial x} dx = \delta(t-t_0) \int_0^1 \phi_n(x) \delta(x-x_0) dx$$

$$= \frac{d a_n}{dt} + \left[\frac{\partial \phi_n}{\partial x} g \right]_0^1 - \int_0^1 \frac{\partial^2 \phi_n}{\partial x^2} g dx = \phi_n(x_0) \delta(t-t_0)$$

So, therefore, we will be getting a_n , which is a function of time, is equal to inner product of g and ϕ_n .

Next, we write $\frac{\partial g}{\partial t} - \frac{\partial^2 g}{\partial x^2} = \delta(x-x_0) \delta(t-t_0)$, the governing equation of g , we take inner product of this equation of g with respect to ϕ_n .

So, we take $\int_0^1 \frac{\partial g}{\partial t} \phi_n dx - \int_0^1 g \frac{\partial \phi_n}{\partial x} dx$ is equal to $\int_0^1 \Delta x \text{ minus } x \text{ naught } \Delta t \text{ minus } t \text{ naught } \phi_n x dx$, from domain of x 0 to 1, 0 to 1.

So, we, since this derivative with respect to space, this respect to $\frac{\partial g}{\partial t}$, this derivative with respect to time and this integral with respect to space, so, I can do the first integration and then I can take the differentiation- absolutely no problem, because derivative is not with respect to x , it is with respect to t whereas, the integration is with respect to space, that is x . So, I take $\frac{\partial}{\partial t}$ out; so, when you bring it outside, this becomes $\frac{d}{dt}$, because $\int_0^1 g \dot{\phi}_n dx$ that will be independent of x after putting the different integral from 0 to 1.

So, this becomes $\frac{d}{dt}$ of integration $g \phi_n dx$ minus, we do it by parts, first function, we take the first function as ϕ_n , integration of second function $\frac{\partial g}{\partial x}$ from 0 to 1, minus minus plus, differential of first function, $d\phi_n dx$, multiplied by integration of the second function, $\frac{\partial g}{\partial x} dx$.

So, since ϕ_n is a sole function of x therefore, this differential with respect to x becomes a total differentiation, and $\frac{\partial g}{\partial x}$ remain as it is, then we write 0 to 1. We integrate this out; so, this integration is with respect to x , so, $\Delta t \text{ minus } t \text{ naught}$ can be taken as common, and it will be out of the integral side, so, it is becomes $\phi_n x \Delta t \text{ minus } x \text{ naught } dx$ 0 to 1.

So, integration of $g \phi_n$ is nothing but inner product of g and ϕ_n , so, this will be nothing but integration $g \phi_n dx$ over 0 to 1. So integration of $g \phi_n$ is nothing but a n t ; so, since a_n is a sole function of t , so, we will be having $\frac{da_n}{dt} \text{ minus } \phi_n \text{ at } x$ is equal to 1 is 0 and $\phi_n \text{ at } x$ is equal to 0 is also 0, because the boundary condition on ϕ_n and homogeneous therefore, after putting the limits we will be getting a 0 contribution out of this, then again, we divide this whole thing becomes 0, we do integration by parts once again, first function integration of second function- so, this plus first function integration of the second function from 0 to 1 minus differential of first function, that is, $\int_0^1 \phi_n^2 dx$ integration of second function $g dx$ from 0 to 1 so, this becomes $\int_0^1 \phi_n x \Delta x \text{ minus } x \text{ naught}$, this becomes $\phi_n x \Delta t \text{ minus } t \text{ naught}$.

Now, let us see what we get? If we open up this part of the bilinear concomitant, we find $\phi_n' \text{ at } 1 \cdot g \text{ at } 1 - \phi_n' \text{ at } 0 \cdot g \text{ at } 0$, but g is having homogeneous boundary condition both at x is equal to 1 and x equal to 0; so this part will also be equal to 0.

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$$\frac{da_n}{dt} - \int_0^1 \frac{d^2 \phi_n}{dx^2} g \, dx = \phi_n(x_0) \delta(t-t_0)$$

$$\boxed{\frac{d^2 \phi_n}{dx^2} + \lambda_n^2 \phi_n = 0}$$

$$\Rightarrow \frac{d^2 \phi_n}{dx^2} = -\lambda_n^2 \phi_n$$

$$\frac{da_n}{dt} + \lambda_n^2 \int_0^1 \phi_n g \, dx = \phi_n(x_0) \delta(t-t_0)$$

$$\underbrace{\int_0^1 \phi_n g \, dx}_{a_n}$$

$$\Rightarrow \boxed{\frac{da_n}{dt} + \lambda_n^2 a_n = \phi_n(x_0) \delta(t-t_0)}$$

Governing equation of a_n

And, so, what will be getting ultimately out of this equation is, $\frac{da_n}{dt} - \int_0^1 \frac{d^2 \phi_n}{dx^2} g \, dx = \phi_n(x_0) \delta(t-t_0)$; and $\frac{d^2 \phi_n}{dx^2} + \lambda_n^2 \phi_n = 0$, so, $\frac{d^2 \phi_n}{dx^2}$ is nothing but $-\lambda_n^2 \phi_n$. We utilize this in the governing equation. This becomes $\frac{da_n}{dt} - \int_0^1 (-\lambda_n^2 \phi_n) g \, dx = \phi_n(x_0) \delta(t-t_0)$, so, $\lambda_n^2 \int_0^1 \phi_n g \, dx = \phi_n(x_0) \delta(t-t_0) - \frac{da_n}{dt}$. We replace $\int_0^1 \phi_n g \, dx$ with a_n , so, $\lambda_n^2 a_n = \phi_n(x_0) \delta(t-t_0) - \frac{da_n}{dt}$.

So, therefore, again, integral of $\phi_n g$ is nothing but a_n , so, $\frac{da_n}{dt} + \lambda_n^2 a_n = \phi_n(x_0) \delta(t-t_0)$; see the development, these gives the governing equation of the coefficient that we have defined whenever, we define the Green's function g . So this gives the governing equation of coefficient a_n , which is a function of time.

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$$\frac{da_n}{dt} + \lambda_n^2 a_n = 0 \quad \text{for } t \neq t_0$$

$$a_n = c \exp(-\lambda_n^2 t)$$

→ generic form of a_n in this equation.

$$a_n^- = A \exp(-\lambda_n^2 t) \quad \text{for } t < t_0^-$$

$$a_n^+ = B \exp(-\lambda_n^2 t) \quad \text{for } t > t_0^+$$

$$\text{At } \underline{t=0, g=0} \Rightarrow a_n^- = 0$$

$$\Rightarrow 0 = A$$

$$\Rightarrow A = 0$$

Next, we solve for a_n . If you look the way we have done earlier, $\frac{da_n}{dt} + \lambda_n^2 a_n$ is equal to 0, for any value of t which is not equal to t_{naught} ; so, except that point, $\frac{da_n}{dt} + \lambda_n^2 a_n$ is equal to 0.

Therefore, the solution of this equation will be is equal to- so, the **Dirac** delta function, the right hand side will be equal to 0 for any value except the point of application of unit impulse, that is, t is equal to t_{naught} - so, a_n will be having a generic form $c \exp(-\lambda_n^2 t)$; so, this is a generic form of solution a_n in this equation.

(0) a_n minus becomes a exponential, so, you can have the lower **half** and upper half solution, minus $\lambda_n^2 t$ for t less than t_{naught} minus, and is equal to $b \exp(-\lambda_n^2 t)$ for t greater than t_{naught} plus. So, we will be having a lower half solution, and this is having an upper half solution, the lower half is less than t_{naught} , the upper half is above of t_{naught} , at t is equal to 0, g is equal to 0, so, therefore, a_n minus is equal to 0; this is the condition on g , so lower half of solution must be satisfying that- so, a_n should be equal to 0 in order to make g is equal to 0.

So, what is left is, a_n minus is equal to 0; if a_n minus is equal to 0, what is left is, this is 0 and **$a \exp$ to the power** put t is equal to 0, so, it will be 1, so, therefore a is equal to 0.

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$a_n = 0 \text{ for } t < t_0 \checkmark$
 $= B \exp(-\lambda_n^2 t) \text{ for } t > t_0$
 jump discontinuity condition:
 $\int_{t_0^-}^{t_0^+} \frac{da_n}{dt} dt + \lambda_n^2 \int_{t_0^-}^{t_0^+} a_n dt = \phi_n(x_0) \int_{t_0^-}^{t_0^+} \delta(t-t_0) dt$
 $\Rightarrow a_n(t_0^+) - a_n(t_0^-) + \lambda_n^2 * 0 = \phi_n(x_0)$
 $a_n(t_0^+) = \phi_n(x_0) = \sqrt{2} \sin(n\pi x)$
 For $t > t_0 \Rightarrow a_n(t) = B \exp(-\lambda_n^2 t)$

So, we can get an expression of a_n now. The expression of a_n is, a_n is equal to 0 for t less than t_0 minus, and this is equal to $b \exp(-\lambda_n^2 t)$ for t greater than t_0 .

Now, we use the jump discontinuity function condition. So, by jump discontinuity condition, let us evaluate it the governing equation, $\frac{da_n}{dt} + \lambda_n^2 a_n$ is equal to $\phi_n(x) \delta(t - t_0)$; so, that was the jump discontinuity, that was the definition of the original problem. Now, we multiply both side by dt and integrate over across the point of application of impulse t_0 minus to t_0 plus.

So, this becomes $a_n(t_0^+) - a_n(t_0^-) + \lambda_n^2 \int_{t_0^-}^{t_0^+} a_n dt$ is a **some** function of t , after multiplying with dt , it will be again be **some** function of t , that function will be evaluated as t_0 plus and t_0 minus, where it will be t_0 plus epsilon and t_0 minus epsilon, and when epsilon tends to 0, you will be basically getting same value minus same value, after putting the boundary limits- so, this will be equal to 0, is equal to $\phi_n(x) \delta(t - t_0) dt$ integral over t_0 minus to t_0 plus, it will be having a value 1 because it is unit impulse, and $a_n(t_0^-)$, we have already seen this is equal to 0, so, this value will be equal to 0; so, $a_n(t_0^+)$ should be is equal to $\phi_n(x)$, so, that will be $\sqrt{2} \sin(n\pi x)$. So, for t greater than t_0 , we have already seen that, $a_n(t)$ is nothing but $b \exp(-\lambda_n^2 t)$; so, therefore, we combine these two equation and see what we get.

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$$a_n(t_0^+) = B \exp(-\lambda_n^2 t_0^+)$$

$$B \exp(-\lambda_n^2 t_0^+) = \sqrt{2} \sin(n\pi x_0)$$

$$B = \sqrt{2} \sin(n\pi x_0) \exp(\lambda_n^2 t_0^+)$$

$$t_0^+ = t_0 + \epsilon \rightarrow 0$$

$$B = \sqrt{2} \sin(n\pi x_0) \exp(\lambda_n^2 t_0)$$

$$a_n = \sqrt{2} \sin(n\pi x_0) \exp[-\lambda_n^2 (t - t_0)] \text{ for } t > t_0$$

$$g(x, t | x_0, t_0) = \begin{cases} 0 & \text{for } t < t_0 \\ \sum_{n=1}^{\infty} \sqrt{2} \sin(n\pi x_0) \sin(n\pi x) \exp[-\lambda_n^2 (t - t_0)] & \text{for } t > t_0 \end{cases}$$

By combining these two equations we will be getting, $a_n(t_0^+)$ is equal to $B \exp(-\lambda_n^2 t_0^+)$, so, we will be getting, $B \exp(-\lambda_n^2 t_0^+)$ is equal to $\sqrt{2} \sin(n\pi x_0)$.

So, we equate these two, and whatever we will be getting is that, we will be getting the constant B now. B will be $\sqrt{2} \sin(n\pi x_0) \exp(\lambda_n^2 t_0^+)$, and if we put $t_0^+ = t_0 + \epsilon$, where $\epsilon \rightarrow 0$, then B becomes $\sqrt{2} \sin(n\pi x_0) \exp(\lambda_n^2 t_0)$.

So, a_n will be nothing but $\sqrt{2} \sin(n\pi x_0) \exp(-\lambda_n^2 (t - t_0))$ for $t > t_0$; and therefore, now, we are in a position to write down the expression of Green's function.

We write down the expression of Green's function as: $g(x, t | x_0, t_0)$ is equal to 0 for $t < t_0$; and this is equal to $\sum_{n=1}^{\infty} \sqrt{2} \sin(n\pi x_0) \sin(n\pi x) \exp(-\lambda_n^2 (t - t_0))$ for $t > t_0$.

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$$g(x, t | x_0, t_0) = H(t - t_0) \sqrt{2} \sum_{n=1}^{\infty} \frac{\sin(n\pi x_0) \sin(n\pi x)}{\exp[-\lambda_n^2 (t - t_0)]}$$

$H \Rightarrow$ Heaviside function.

$$H(t - t_0) = \begin{cases} 0 & \text{for } t < t_0 \\ 1 & \text{for } t > t_0 \end{cases}$$

To evaluate adjoint operator.

$$L = \frac{\partial}{\partial t} - \frac{\partial^2}{\partial x^2}$$

$$\langle Lu, v \rangle = \int_V v \left(\frac{\partial u}{\partial t} - \frac{\partial^2 u}{\partial x^2} \right) dV$$

$$= \iint_V v \frac{\partial u}{\partial t} dt dx - \iint_{\partial V} v \frac{\partial u}{\partial x^2} dx dt.$$

So, we write it down, the value, the expression of g in a more compact form. If we write it down in a more compact form, this becomes $g(x, t | x_0, t_0)$ is equal to $H(t - t_0)$ times $\sqrt{2}$ times summation from $n=1$ to infinity of $\sin(n\pi x_0) \sin(n\pi x) \exp[-\lambda_n^2 (t - t_0)]$, where n is equal to 1 to infinity.

So, where H is the heavy side function, and its definition is, $H(t - t_0)$ is equal to 0 for $t < t_0$, and this is equal to 1 for $t > t_0$. So, that is the definition of the heavy side function, and this gives the solution of Green's function.

So, we get the complete solution of Green's function for the parabolic operator. Next we check whether the adjoint operator is same as the operator we are dealing with or it is different, and if it is different, what is that? So, next step is to evaluate adjoint operator; if you look into the operator, this will be $\frac{\partial}{\partial t} - \frac{\partial^2}{\partial x^2}$.

So, let us find out what the operator is; inner product, same way we have done earlier in the case of ordinary differential equation, so, inner product of Lu and v will be nothing but integration over volume $\int_V v \frac{\partial u}{\partial t} dt - \int_V \frac{\partial^2 u}{\partial x^2} v dx$; so, it will be double integration- because this dV is, it is a two-dimensional problem, it will be $dt dx$, so, it will be double integration one over t another over x - so, it will be $\int_V v \frac{\partial u}{\partial t} dt dx - \int_V \frac{\partial^2 u}{\partial x^2} v dx dt$. So, this becomes $\int_V v \frac{\partial u}{\partial t} dt dx - \int_V \frac{\partial^2 u}{\partial x^2} v dx dt$. So, we carry out the integration by parts.

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$$\begin{aligned}
 \langle Lu, v \rangle &= \int_0^1 \int_t^\infty v \frac{\partial u}{\partial t} dt dx - \int_0^1 \int_t^\infty v \frac{\partial^2 u}{\partial x^2} dx dt \\
 &= \int_0^1 \left[v u \Big|_0^t - \int_0^1 \frac{\partial v}{\partial t} u dt \right] dx \\
 &\quad - \int_0^1 \left[v \frac{\partial u}{\partial x} \Big|_0^t - \int_0^1 \frac{\partial v}{\partial x} \frac{\partial u}{\partial x} dx \right] dt \\
 &= \int_0^1 [v(t) u(t) - u(0) v(0)] - \int_0^1 \frac{\partial v}{\partial t} u dt dx \\
 &\quad + \int_0^1 \frac{\partial v}{\partial x} \frac{\partial u}{\partial x} dx dt.
 \end{aligned}$$

So, inner product of $L u$ and v will be, let us write it down, $v \frac{\partial u}{\partial t}$ minus $\frac{\partial}{\partial t} \int_0^1 v \frac{\partial^2 u}{\partial x^2} dx$ minus double integral one over t another over x $v \frac{\partial^2 u}{\partial x^2} dx dt$. So, first function, second function.

So, integration over x remaining first function integral of the second function over 0 to t minus differential of first function $\frac{\partial v}{\partial t}$ and integration of the second function, that is $u dt$ then dx minus integration over t first function differential of second function $\frac{\partial u}{\partial x}$ 0 to 1 minus differential of first function integration of the second function $\frac{\partial v}{\partial x} \frac{\partial u}{\partial x} dx dt$.

So, what we are getting that, at v is equal to, for t greater than t naught, we have already obtained that t greater than t 1 v is equal to 0 , so, we put it, $v(t) u(t)$ at t minus $u(0) v(0)$, that is, 1 minus integration over x over t $\frac{\partial v}{\partial t} u dt dx$, that is, the first one minus integration over t - now, since we have the homogeneous boundary condition, so, v at x is equal to 1 , v at x is equal to 0 both of them will be 0 , so, these will be 1 , so, this will be contributing 0 - so, minus minus plus, you will be having, $\frac{\partial v}{\partial x} \frac{\partial u}{\partial x} dx dt$, and in this case the homogeneous boundary condition at t is equal to 0 , so, u will be is equal to 0 , and v is equal to 0 for any t greater than 0 , so, this term also be off.

So what will be having is, minus double integral $\frac{\partial v}{\partial t} u dt dx$, and one more integration here, first function integration of the second function plus first function $\frac{\partial v}{\partial x} \frac{\partial u}{\partial x} dx dt$.

del x integration of second function u from 0 to 1 minus differential of second function, that is, del square v del x square integration of the first one that will be u d x, then d t.

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$$\begin{aligned}
 \langle L u, v \rangle &= - \iint u \frac{\partial v}{\partial t} dt dx \\
 &\quad + \int_t (-1) \int_0^1 \frac{\partial^2 v}{\partial x^2} u dx dt \\
 &= \iint_t \left(-\frac{\partial v}{\partial t} - \frac{\partial^2 v}{\partial x^2} \right) u dx dt \\
 &= \langle u, L^* v \rangle \quad \left| \begin{array}{l} L^* = \frac{\partial}{\partial t} - \frac{\partial^2}{\partial x^2} \\ L \neq L^* \end{array} \right.
 \end{aligned}$$

So, let us see what we get. We get $L u$ and v should be is equal to minus double integral $u \frac{\partial v}{\partial t} dt dx$ plus double integral integration over t and then u at x is equal to 1 and u at x is equal to 0 will be 0 so there will be a minus sign there and it becomes integral del 0 to 1 del square v del x square times $u dx dt$

So, ultimately, what we will be obtaining is that double integral 1 over t another over x minus del v del t minus del square v del x square $u dx dt$

So, you will be getting inner product of $u L^* v$ so if you $L^* v = u L^* v$ so if you look into the L^* the adjoint operator is minus del del t minus del square del x square and if you see the actual operator the original operator it was del del t minus del square del x square

So, therefore, L is not is equal to L^* , so, L is not equal to L^* , and it, the problem is not a self adjoint problem. So, therefore, we have to evaluate the adjoint Green's function, then connect the adjoint Green's function with the original problem, u .

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$$\begin{aligned}
 &\checkmark Lg(x, t | x_0, t_0) = \delta(x - x_0) \delta(t - t_0) \\
 &\checkmark L^* g^*(x, t | x_1, t_1) = \delta(x - x_1) \delta(t - t_1) \\
 &-\frac{\partial g^*}{\partial t} - \frac{\partial^2 g^*}{\partial x^2} = \delta(x - x_1) \delta(t - t_1) \\
 &\text{at } t=0 \Rightarrow g^* = 0 \\
 &\text{at } x=0 \Rightarrow g^* = 0 \\
 &\iint g^* \frac{\partial g}{\partial t} dt dx - \iint g^* \frac{\partial^2 g}{\partial x^2} dx dt \\
 &+ \iint g \frac{\partial g^*}{\partial t} dt dx + \iint g \frac{\partial^2 g^*}{\partial x^2} dx dt \\
 &= g^*(x_0, t_0 | x_1, t_1) - g(x_1, t_1 | x_0, t_0)
 \end{aligned}$$

So, next step is obtaining the adjoint Green's function. This was the original Green's function, casual Green's function; so, this will be delta x minus x naught delta t minus t naught and adjoint Green's function is L star g star x t x naught x 1 t 1 is equal to delta x minus x 1 delta t minus t 1.

So, if you write down the adjoint operator, L star, this becomes minus del g star del t minus del square g star del x square is equal to delta x minus x 1 delta t minus t 1, and at t is equal to 0, and g star is equal to 0 at x is equal to 0, and 1 your g star is equal to 0. Similarly, so, these are the conditions, this is the condition on g, at least on g.

We know these are the conditions on g, now, let us find out the conditions on g star. For that what we have to do? We have to take the inner product with this equation with respect to g star, we have to take the inner product of this equation with respect to g and then we will subtract, if you do that what will be getting is that, inner product double integral g star del g del t d t d x minus double integral g star del square g del x square d x d t plus, minus minus plus, so, it will be, g del g star del t d t d x, double integral g del square g star del x square d x d t, and this will be is equal to g star x naught t naught slash x 1 t 1 minus g x 1 t 1 slash x 0 t 0.

So, if we do that, we combined these two part and combined these two part, we have already seen, if we differentiate with respect to, if we integrate this thing by parts, then

we will be getting the term that will be equal to 0. Similarly, if we evaluate this integration by parts again, we will be getting a 0.

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$$\int_x \int_t \frac{d}{dt} (g g^*) dt dx = g^*(x_0, t_0 | x_1, t_1) - g(x_1, t_1 | x_0, t_0)$$

$$\int_x \left[g g^* \Big|_t - g g^* \Big|_{t=0} \right] dx = g^*(x_0, t_0 | x_1, t_1) - g(x_1, t_1 | x_0, t_0)$$

for $t > t_1$,

$g^* = 0 \text{ for } t > t_1$

$$g^*(x_0, t_0 | x_1, t_1) = g(x_1, t_1 | x_0, t_0)$$

So, ultimately, whatever we will be getting is double integral x and t of g and g^* , when you combine these two, $dt dx$ will be nothing but $g^* x$ naught t naught x 1 t 1 minus $g x$ 1 t 1 x 0 t 0. Now, integration over x , which is $g g^*$ at t minus $g g^*$ at t is equal to 0 dx that should be is equal to $g^* x$ 0 t 0 x 1 t 1 minus $g x$ 1 t 1 x 0 t 0.

So, we know that g at time t is equal to 0 equal to 0, so, this part will be gone, and to make this bilinear concomitant term to be 0, we put for t greater than t_1 g^* is equal to 0 for t greater than t_1 .

If we have this boundary condition, then this will be gone and we will be getting the conventional nomenclature that is, $g^* x$ naught t naught slash x 1 t 1 should be equal to $g x$ 1 t 1 slash x naught t naught.

Now, we are in a position, since we have obtained this relationship, and we have already obtained the expression of g , we can get the expression of g^* - you need not solve the partial differential equation once again; if we do that what will be getting is that as follows:

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$$g(x, t | x_0, t_0) = H(t - t_0) \sum_{n=1}^{\infty} \frac{\sqrt{2} \sin(n\pi x) \sin(n\pi x_0)}{e^{-\lambda_n^2 (t - t_0)}}$$

Change, $x, t \rightarrow x_1, t_1$

$$g(x_1, t_1 | x_0, t_0) = H(t_1 - t_0) \sum_{n=1}^{\infty} \frac{\sqrt{2} \sin(n\pi x) \sin(n\pi x_0)}{e^{-\lambda_n^2 (t_1 - t_0)}}$$

$$g^*(x_0, t_0 | x_1, t_1) = H(t_1 - t_0) \sum_{n=1}^{\infty} \frac{\sqrt{2} \sin(n\pi x) \sin(n\pi x_0)}{e^{-\lambda_n^2 (t_1 - t_0)}}$$

Change, $x_0, t_0 \rightarrow x, t$

$$g^*(x, t | x_1, t_1) = H(t_1 - t) \sum_{n=1}^{\infty} \frac{\sqrt{2} \sin(n\pi x) \sin(n\pi x_1)}{e^{-\lambda_n^2 (t_1 - t)}}$$

If you remember, the expression of g is equal to $H(t - t_0)$ summation root over 2 $\sin n\pi x \sin n\pi x_0$ $e^{-\lambda_n^2 (t - t_0)}$.

Now, we change the nomenclature x, t to x_1, t_1 . So, this gives $g(x_1, t_1 | x_0, t_0)$ is equal to $H(t_1 - t_0)$ root 2 $\sin n\pi x \sin n\pi x_0$ $e^{-\lambda_n^2 (t_1 - t_0)}$ n is equal to 1 to infinity; now, $g(x_1, t_1 | x_0, t_0)$ is nothing but g^* , so, this becomes $g^*(x_1, t_1 | x_0, t_0)$ is equal to $H(t_1 - t_0)$ summation root 2 $\sin n\pi x \sin n\pi x_0$ $e^{-\lambda_n^2 (t_1 - t_0)}$.

Now, what we do? We change- so, this is nothing **but $g^*(x_0, t_0 | x_1, t_1)$** , this is same as $g^*(x_0, t_0 | x_1, t_1)$, so, we change the nomenclature x_1, t_1 to x and t ; so, this becomes $g^*(x_0, t_0 | x, t)$ is equal to $H(t_1 - t)$ summation root over 2 $\sin n\pi x \sin n\pi x_0$ $e^{-\lambda_n^2 (t_1 - t)}$, so, this becomes t_1

When you change x and t to x_1, t_1 , this becomes t_1 , this remains t_1 , this remains t_1 and then we substitute, we replace t_0 by t . So, this is the governing equation.

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$$H(t_1 - t) = \begin{cases} 0 & \text{for } t_1 < t \\ 1 & \text{for } t_1 > t \end{cases}$$

So, $g^* = 0$ for $t > t_1$

$$= \sum_{n=1}^{\infty} \sqrt{2} \sin(n\pi x_1) \sin(n\pi x) e^{-\lambda n^2 (t_1 - t)} \quad \text{for } t < t_1$$

Now, if you remember, what is the definition of $t_1 - t$ heavy side function... so, the heavy side function will be like this: the heavy side $H(t_1 - t)$ is equal to 0 for t_1 less than t , and it is 1 for t_1 greater than t . So, g^* is equal to 0 for t greater than t_1 , and g^* is equal to summation root over 2 n is equal to 1 to infinity $\sin n\pi x_1 \sin n\pi x e$ to the power minus $\lambda n^2 t_1 - t$ for t less than t_1 .

So, that is the expression of the adjoint Green's function, we have derived in this expression, in this equation. So, if you remember, whatever we have done, we really did not solve the governing equation of g^* , we solved the governing equation of g , and obtained the definition of expression of g^* , then by utilizing the property, g is equal to g^* , we change the subscripts of the variables x and t , and ultimately we got an expression of g^* .

And we have seen for t greater than t_1 , g^* is equal to 0, and for t less than t_1 , g^* is not equal to 0, and that will be given by this expression root over 2 $\sin n\pi x_1 \sin n\pi x e$ to the power minus $\lambda n^2 t_1 - t$.

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Final Solution

$$-\frac{\partial g^*}{\partial t} - \frac{\partial^2 g^*}{\partial x^2} = \delta(x-x_1) \delta(t-t_1) \quad \dots (2)$$

$$\frac{\partial u}{\partial t} - \frac{\partial^2 u}{\partial x^2} = f \quad \dots (1)$$

$\langle 1, g^* \rangle - \langle 2, u \rangle$

$$\iint g^* \frac{\partial u}{\partial t} dx dt - \iint \frac{\partial^2 u}{\partial x^2} g^* dx dt + \iint u \frac{\partial g^*}{\partial t} dx dt + \iint \frac{\partial^2 g^*}{\partial x^2} u dx dt = \iint f g^* dx dt - u(x_1, t_1)$$

LHS RHS

Now, what is left is, the left is, the connection of adjoint Green's function and the original problem u , by doing some inner product method that is required. So, let us look into the final solution; we are almost at the final step, the final solution is, let us write down the governing equation of, **del g star**, of adjoint Green's function.

So, this will be minus del g star del square g star del x square is equal to delta x minus x 1 delta t minus t 1- this is equation number two; and del u del t minus del square u del x square is equal to f- this is equation number one.

Then, what we do, we take inner product with g star and minus inner product of 2 with u and then subtract, so, if you do that what you will be getting is- g star del u del t d x d t minus double integral del square u del x square g star d x d t plus double integral u del g star del t d x d t, minus minus plus, so, it will be del square g star del x square u d x d t.

On the right hand side you will be having integration double integral f g star d x d t minus u as a function of x 1 t 1, because the it is integral of u delta x x minus 1 delta t minus delta x x minus 1 delta t minus t 1 and d x d t, so, it will be u of x 1 t 1.

So, therefore, what will be getting is, is this equation. Now, what we do, we look into the left hand side of the equation- so, this is the left hand side, this is the right hand side- if you look into the left hand side, let us see what we get out of this.

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$$\begin{aligned}
 \text{LHS} &= \iint \left(g^* \frac{\partial u}{\partial t} + u \frac{\partial g^*}{\partial t} \right) dt dx \\
 &\quad - \iint \frac{\partial^2 u}{\partial x^2} g^* dx dt + \iint \frac{\partial^2 g^*}{\partial x^2} u dx dt \\
 &= \int_{x=0}^1 \int_0^{t_1} \frac{d}{dt} (u g^*) dt dx - \int_0^{t_1} \left[g^* \frac{\partial u}{\partial x} \Big|_0^1 - \frac{\partial g^*}{\partial x} \frac{\partial u}{\partial x} \Big|_0^1 \right] dt \\
 &\quad + \int_0^{t_1} \left[u \frac{\partial g^*}{\partial x} \Big|_0^1 - \frac{\partial g^*}{\partial x} \frac{\partial u}{\partial x} \Big|_0^1 \right] dx \\
 &= \int_{x=0}^1 \left[u g^* \Big|_{t=t_1} - u g^* \Big|_{t=0} \right] dx \\
 &\quad + \int_0^{t_1} \left[u(1) \frac{\partial g^*}{\partial x}(x=1) - u(0) \frac{\partial g^*}{\partial x}(x=0) \right] dt.
 \end{aligned}$$

The left hand side becomes very complicated, this is inner product of double integral $g^* \frac{\partial u}{\partial t}$ plus $u \frac{\partial g^*}{\partial t}$ minus double integral $\frac{\partial^2 u}{\partial x^2} g^*$ plus double integral $\frac{\partial^2 g^*}{\partial x^2} u$.

So, it will be 0 to 1 over x , and 0 to t_1 over t , and it will be $dt dx$ of $u g^*$ because g^* , this limit over t is, to simply say that confirm g^* is not equal to 0 for t less than t_1 , and g^* , anything above t_1 it will be equal to 0, therefore, we have to put the limit from 0 to t_1 because g^* is not equal to 0 within that domain, it exists there- minus over t first function by integration by part first function integral of second 1 from 0 to 1 minus $\frac{\partial g^*}{\partial x} \frac{\partial u}{\partial x} \Big|_0^1$, dx times dt plus we have integration over time, so, it becomes $u \frac{\partial g^*}{\partial x} \Big|_0^1$ minus integration $\frac{\partial g^*}{\partial x} \frac{\partial u}{\partial x} \Big|_0^1$; so, if you look into this equation this is minus minus plus $\frac{\partial g^*}{\partial x} \frac{\partial u}{\partial x} \Big|_0^1$, and this is minus $\frac{\partial g^*}{\partial x} \frac{\partial u}{\partial x} \Big|_0^1$; so, this will be plus, this will be minus, so these two will be cancelled out.

So, we have x is equal to 0 to 1 and then integration of this $u g^*$ evaluated at t is equal to t_1 minus, $u g^*$ evaluated at t is equal to 0 dx , that is the first part.

And now, we put the second one, plus 0 to t_1 u at x is equal to 1 $\frac{\partial g^*}{\partial x}$ at x is equal to 1 minus u at x is equal to 0 $\frac{\partial g^*}{\partial x}$ at x is equal to 0 dt .

The other parts of bilinear concomitant like g^* at 1, and g^* at 0 will be 0, and u at 1, and u at 0, they are not equal to 0, they are non-homogeneous; so, therefore, we put this term there.

So, now, let us see what we get out of this. And at t is equal to t_1 , g^* is equal to 0, for that this term will be off, so, whatever is left on the left hand side is this:

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$$\begin{aligned}
 \text{LHS} &= - \int_0^1 h g^*|_{t=0} dx + \int_0^{t_1} q \frac{\partial g^*}{\partial x}|_{x=1} dt \\
 &\quad - \int_0^{t_1} p \frac{\partial g^*}{\partial x}|_{x=0} dt \\
 \text{RHS} &= \int_0^{t_1} \int_0^1 f g^* dx dt - u(x_1, t_1) \\
 u(x_1, t_1) &= \int_0^{t_1} \int_0^1 f g^* dx dt + \int_0^1 h g^*|_{t=0} dx - \int_0^{t_1} q \frac{\partial g^*}{\partial x}|_{x=1} dt \\
 &\quad + \int_0^{t_1} p \frac{\partial g^*}{\partial x}|_{x=0} dt
 \end{aligned}$$

$u(x, t)$

So, left hand side, we have minus 0 to 1 and g^* at 0 to 1, and u at 0 to u at 0 becomes h so $h g^*$ at t is equal to 0 dx plus 0 to t_1 $q \frac{\partial g^*}{\partial x}$ at x is equal to 1 dt minus integration $p \frac{\partial g^*}{\partial x}$ at x is equal to 0 dt , so, this will be over 0 to t_1 , this will be over 0 to t_1 .

So, if you look into the right hand side, the right hand side is double integral 0 to t_1 0 to 1 $f g^* dx dt$ is equal to minus $u(x_1, t_1)$.

So, now, if we take u on the right hand side, u becomes, $u(x_1, t_1)$ becomes 0 to t_1 0 to 1 $f g^* dx dt$ plus 0 to 1 $h g^*$ evaluated at t is equal to 0 dx minus 0 to t_1 $q \frac{\partial g^*}{\partial x}$ at x is equal to 1 dt , minus minus plus, integral 0 to t_1 $p \frac{\partial g^*}{\partial x}$ at x is equal to 0 dt .

And this h , q and p , if they are constant, we just take them outside of the integral and carry out this integration. Now, if you see on the right hand, there are four terms, there are three sources of non-homogeneity in the governing equation u at t is equal to 0; so,

this corresponds to that non-homogeneous term at x is equal to 0, u was equal to p , so, this correspond to that non-homogeneous term at x is equal to 1 u was equal to q .

So, this corresponds to that non-homogeneous term, and this non-homogeneous term occurs because of the non-homogeneous term appearing in the governing equation; if you see, there are two boundary conditions on x , those are non homogeneous, so, you have line integral over them, and they will be integrated over time.

There was one non-homogeneous term in the initial condition, so, this corresponds to that one line integral over x corresponding to the one non-homogeneous term in the initial condition, there was one non-homogeneous term in the governing equation, since it is valid throughout the whole control volume, we will have a double integral corresponding to the whole control volume. So, there will be double integration over f and g star in the whole control volume.

So, since there are four sources of non-homogeneity in the governing equation, one non-homogeneity the main equation and three non-homogeneities in the initial and boundary conditions, there are four terms appearing on the right hand side.

And next, we carry out this integration over t 1 and x , and we change the index from, the running index from, running variables x 1 t 1 to x and t , we will be getting the solution of u as a function of x and t .

So, I stop here in this class. In tomorrow's class, what I will do, I will really evaluate these integrals one after another and will obtain the complete solution of u as a function of x and t for a parabolic partial differential equations, which is non-homogeneous using the Green's function method. Thank you very much.