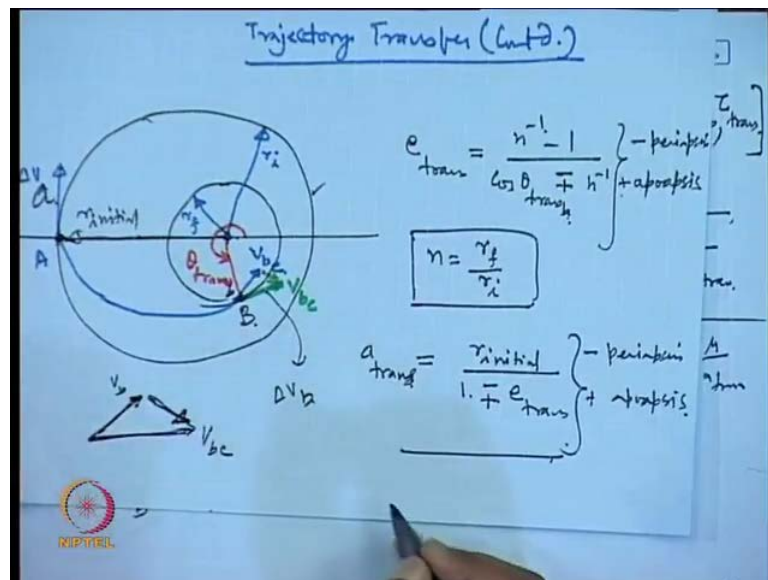


Space Flight Mechanics
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Lecture no.# 28
Trajectory Transfer(Contd.)

We have been discussing about the trajectory transfer, so co planner maneuver we were working out, and one tangent bond we had started, so we will complete it today.

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So, we had one outer orbit, in which the satellite was at this point, and there was an inner orbit, and then after giving one tangent bond at this place delta v A, it was brought to this place and then another bond was given here in this place, so this is v B in elliptical orbit, we show it by e. So, r i is the initial radius and r f is the final radius, and the true anomaly of this point was written as theta trans. And then we develop the equations which were, cos theta trans of the transfer orbit at the point B. So this subscript b is appearing, so here the minus sign is for periapsis, and plus sign for apoapsis. So, if you start here in this point then you take the plus sign. If you start here in this point then you take the negative sign, and n is written as r f by r i. So, using this information we calculated the a transfer orbit a eccentricity of the transfer orbit, and next we computed also, semi major of the

transfer orbit, so this was given by r initial. So, in reality we will be given with two orbits, either it may be circular or it may be elliptical, and the true anomaly will be given. Initial position of the satellite will available to you. So, this is r initial position from here to here, this is r initial. And of course, this radius of this circle, if it is a circle the final orbit then this is given as r final.

(Refer Slide Time: 04:00)

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Steps involved [$r_{initial}, r_{final}, \theta_{trans} \rightarrow e_{trans}, a_{trans}, \tau_{trans}$]
 Given $\Delta v_a, \Delta v_b$

(1)

$$v_{initial} = \sqrt{\frac{\mu}{r_{initial}}}$$

$$v_{final} = \sqrt{\frac{\mu}{r_{final}}}$$

$$v_{trans_a} = \sqrt{\frac{2\mu}{r_{initial}} - \frac{\mu}{a_{trans}}}$$

$$v_{trans_b} = \sqrt{\frac{2\mu}{r_{final}} - \frac{\mu}{a_{trans}}}$$

$$\Delta v_a = v_{trans_a} - v_{initial}$$

$$v_b = \sqrt{v_{trans_b}^2 + v_{final}^2 - 2v_{trans_b} \cdot v_{final} \cos \phi_b}$$

And thereafter after doing this, we can work out rest of the things. So, the steps involved, so these are the quantities given, so from here you have to determine eccentricity of the transfer orbit, a transfer orbit and the time for transferring from a to b, and of course, delta v A and delta v B, the impulses required at the two points A and B, so this is your this is point B and this is point A. So here the how much impulses required, this will be denoted by delta v and this is delta v A. And we can remove the sign just we are, because we are showing it in this direction, so no need of showing the sign, so this basically we need to de boost in this place, and again here we have to bring it in the smaller orbit so we need to de boost it. So, here this is the v b c, the velocity at point b in the circular orbit if it is a circular orbit, and this is the impulse and required to bring it to this. So, let us compute this quantities one by one; v initial if the outer orbit is a circular orbit, so this simply written as mu by r initial under root.

The next you have v final you can write as mu by r final under root, and v in the transfer orbit at point a this will be 2 mu by r initial minus 1 mu by a transfer orbit square root.

And at point b in the transfer orbit, this is μ by r final minus μ by a trans under root. So, first you have to need to compute all this quantities then Δv_b will be given as. Let us first compute Δv_a , so $v_{trans a}$ minus $v_{initial}$. Similarly, Δv will be given by. Now in the case of Δv_b which is shown by this small green line, here it is difficult to see it, but it is appearing something like this is v_b , and suppose this is $v_{b c}$, so then you need to give. This, vector is larger so you need to give boost it here in this place. So, this will be quantity here Δv_b . So, Δv_b will be given by $v_{trans b}$ square and then v_{final} square minus two, $v_{trans b}$ times, v_{final} times $\cos \phi_b$, where ϕ_b is the flight path angle at b.

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$|\Delta v| = |\Delta v_a| + |\Delta v_b|$
 $\cos \phi_b = \frac{1 + e \cos \theta}{\sqrt{1 + 2e \cos \theta + e^2}}$
 $\sin \phi_b = \frac{e \sin \theta}{\sqrt{1 + 2e \cos \theta + e^2}}$
 $\tan \phi_b = \frac{e \sin \theta}{1 + e \cos \theta}$
 $\cos E = \frac{e_{trans} + \cos \theta_{trans}}{1 + e_{trans} \cos \theta_{trans}}$
 $E \rightarrow \text{eccentric anomaly}$

So the total velocity change required Δv will be Δv_a plus Δv_b . The flight path angle $\cos \phi_b$ can be written as, $1 + e \cos \theta$ divided by $1 + 2e \cos \theta + e^2$ under root. And $\sin \phi_b$ can be written as $e \sin \theta$, where you can look that how we define the angles again I am repeating. If this is the v direction, this is the radius direction, so this is the radius vector in this direction, and this is θ direction, then this is your ϕ , and this angle is your θ which gives you the true anomaly. So, we are measuring from the perigee position. And $\tan \phi_b$ this will be written as $e \sin \theta$ by $1 + e \cos \theta$. So, these are the relationship that you can derive and all this things we have worked out earlier, so no need of repeating in this place again. Now, what you need to do here, find out the eccentric anomaly using this equation. So, look into earlier lectures we have developed all this things. So, $e_{trans} + \cos \theta_{trans}$ b

divided by 1 plus e trans, eccentricity of the transfer orbit, times cos theta transfer orbit at b, and where E is the eccentric anomaly, you need this quantity I am going to explain.

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Handwritten mathematical derivations on a blue background:

- Mean motion: $n = \sqrt{\frac{\mu}{a^3}} \Rightarrow \frac{2\pi}{T} = \sqrt{\frac{\mu}{a^3}}$
- Period: $T = 2\pi \sqrt{\frac{a^3}{\mu}}$
- Conservation of angular momentum: $r^2 \frac{d\theta}{dt} = h$
- Integration: $\int dt = \int \frac{r^2}{h} du$
- Final equation for time of flight: $t_{trans} = \sqrt{\frac{a^3}{M}} \left[\frac{2k\pi + (E - e_{trans} \sin E) - (E_0 - e_{trans} \sin E_0)}{M_B - M_A} \right]$

Say, if you want to find out the flight time from A to B, so you need to integrate the equation, which earlier we have written as r square theta dot equal to h, and this often this was written as d by d t equal to h by r square. And for finding out the d t, this was integrated and this is r square by h d theta, we integrated this and you know that while working with the Kepler's equation, so we did all these things. So the same equation we have chosen here in this place, so while working for the Kepler's equation, we derived this relationship and the same relationship we are using here. Now if you use the true anomaly, so finding out the time then you need to integrate the equation, so to avoid that we work in terms of the eccentric anomaly. So, the flight time will be given by, now the flight time taken, that will be obviously if we are expressing in terms of, this is an elliptical orbit and here the angular rate is obviously varying as the r varies.

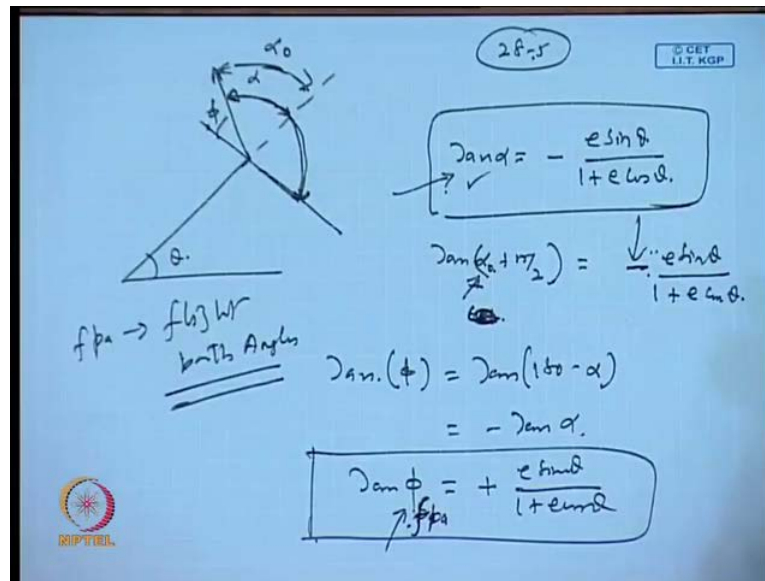
And therefore the angular rate, you can see from this place h is a constant, and therefore as the r varies the angular rate, the theta dot which is, it keeps varying, therefore, instead of using a changing theta which needs the integration of this equation. So we use the mean angular rate, and mean angular rate obviously you know, that for mean angular rate this is given by mu by a cube under root and obviously from this place you can write 2 pi by t equal to mu by a cube under root, and t becomes 2 pi times a cube by mu under root.

So this is the time period of the satellite to complete one orbit. So if it starts from here and if you leave here, so it will come back after this much of period, where a is the semi major axis of the transfer orbit. Now, we do not want to use this particular equation given here. So, rather we will write the whole thing in terms of the eccentric anomaly.

So τ transfer, this will be given as. Now, you can look from this place, this is for 2π , if you have to go through by 2π radian then you need this much of time, which is indicated by capital T and if you have to go by some smaller angle say θ , so you need a smaller amount of time. So, here the θ instead of working in terms of θ , we are just indicating using this mean angular rate, which is given by μ/a^3 . So, here this will become a^3/μ under root times. Now, suppose you let the satellite go again and again in this orbit. It is going from here to here, passing here, coming here. So it may go k times and after that you are carrying out the maneuver. So, you need to include all those angles here, so this can be written as $2k\pi$. This is for the repetition how many times you are repeating that orbit, plus $E - e \sin E$.

So this is the eccentric anomaly of this point, and this is the eccentric anomaly from where you are starting, this point. So we are starting here in this point, and this is your elliptical orbit which is getting completed like this. So, eccentric anomaly of this point and what is the eccentric anomaly of this point, so you have to subtract like this. And this quantity is nothing, but we are writing in terms of the eccentric anomaly, so this is nothing, but your mean anomaly. So, mean anomaly of point B and this is mean anomaly of point A. So this gives you the transfer times which is required, if k is equal to 0 means, in the first shot only you are going to transfer it. So k will be equal to 0 and only these quantities are required.

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Now we have done this, so last time the problem which we left out. So what we need to do now, is to complete that and before completing that the equations that I have used I will just work it out for you. This $\cos \phi$ and $\sin \phi$, it is easy to see that, if this angle is θ and this angle is ϕ , and earlier we defined this angle. If you look into earlier lecture we defined this angle as α . So, either we can define this angle as α or either I can define the angle from here to here as α , and depending on how you are defining this angle α , the equations for $\tan \alpha$ changes. So if you define $\tan \alpha$ from here to here, so this becomes $\tan \alpha$ equal to minus $e \sin \theta$ by one plus $e \cos \theta$, and this we have worked out earlier.

But we worked out by writing here α from this place to this place, now we have shown the α from here to here. If you want to do other way, so what you need to do. If you indicate α say from here to here, so let us say this quantity is α_0 you are writing. So $\tan \alpha_0$, you want to indicate it in terms of $\tan \alpha_0$, so the same here α will become $\alpha_0 + \pi/2$. And this is the quantity on the right hand side, so this quantity becomes \cot . So either you express it in this way so from here you can get the value of α_0 , or either you express it in this way, both are possible so. If we take this option then we have the working out for ϕ here. So we can directly write ϕ equal to $\tan \phi$ equal to $\tan 180$ minus α , and this becomes \tan minus $\tan \alpha$. So this minus $\tan \alpha$ you can put from this place, so this is $e \sin \theta$ by $1 + e \cos \theta$. And

this is what we are interested in, and where phi is the flight path angle. This is f p a flight path angle.

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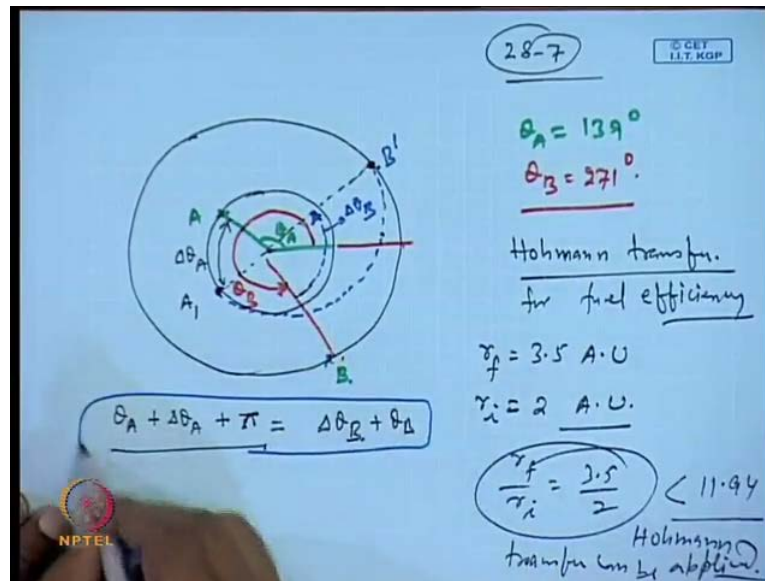
$$\sin \phi = \frac{\sinh \phi}{\cosh \phi} = \frac{\tanh \phi}{\sec \phi} = \frac{\tanh \phi}{\sqrt{1 + \tanh^2 \phi}}$$

$$= \frac{e \sin \theta}{\sqrt{1 + 2e \cos \theta + e^2}}$$

$$\cos \phi = \frac{1 + e \cos \theta}{\sqrt{1 + 2e \cos \theta + e^2}}$$

Once, this is known to you, then sin phi simply you can write as; sin phi by cos phi times cos phi. So this becomes tan phi divided by sec phi, 1 plus tan square phi under root. And insert the value for tan phi here and the value for the sin phi you get as, e sin theta divided by 1 plus 2 a cos theta plus c a square under root. And similarly, cos phi you can get as 1 plus e cos theta divided by 1 plus 2 e cos theta plus e square under root. It is easy to working out, you just look in to other lectures and you can complete it.

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Now, we complete the last time problem. The last time we left it, because this problem was bit lengthy and I did not to cover it in this one go. So the problem given was the first part we were working out, that we have two heliocentric orbits, in which one asteroid was at the point A another asteroid was at point B, where this angle was say the theta A, so theta a was giving to be 139 degree, and the angle from here to here, so this angle was theta B and theta B was given to be 271 degree. Now the problem was that, some satellite is to be launched from A, A is moving B is also moving and this satellite has to catch up B. So, the requirement was also that we have to do the Hohmann transfer, Hohmann transfer for fuel efficiency for saving the propellant.

And obviously this case r final was given to the 3.5 astronomical unit, and r initial was given to the 2 astronomical units. And therefore, r f by r i, this is 3.5 divided by 2. This is less than 11.94, and therefore Hohmann transfer can be applied, and it will be fuel efficient. But before catching this, so Hohmann transfer can be applied such that, if you are suppose you are applying the Hohmann transfer in this place, so at that time while the satellite is catching B, so B must come out to be here in this point. So exactly the pi degree, pi radian the satellite has to move from this point to this point. So this point we termed as A 1 from where, and this angle we wrote as delta theta A. and then the satellites was launched from here to here, and it went and caught up the asteroid B at the point B prime.

So in the first go what we have worked out that, theta A plus delta theta A, plus the angle from here to here which is nothing but pi. This could be equal to the angle which B will move from here to here that it will cover, so that was delta theta B plus theta B. So this angle from here to here and then from here to this place. And from this place to this place, this is total angle here and from here to here this is angle your theta B. And from this place to this place this is, so we can show it here. This angle is from this place to this place, this angle is your delta theta B. So this must equalize, obviously it is apparent from our figure.

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Handwritten calculations on a blue background:

$$a = \frac{r_{initial} + r_{final}}{2} = \frac{2 + 3.5}{2} \text{ A.U.} = 2.75 \text{ A.U.}$$

$$\omega_A = 7.0393902 \times 10^{-8} \text{ rad/s}$$

$$\omega_B = 3.0407308 \times 10^{-8} \text{ rad/s}$$

$$T_{1/2} = \pi \cdot \sqrt{\frac{(2.75 R)^3}{\mu}} = \frac{71956309}{\text{seconds}}$$

Additional calculations and conversions:

- $R = 1 \text{ A.U.}$
- $R = 1.49596 \times 10^8 = 1 \text{ A.U. km}$
- $\mu = 1.32715 \times 10^{11} \text{ km}^3/\text{s}^2$
- Final result: 832.82765 days
- Conversion: $\frac{71956309}{24 \times 3600}$

Because it is a Hohmann transfer and in this transfer orbit we are boosting at point A one. So this is basically you are doing the firing the rocket at the perigee of this transfer orbit. And this is the apogee point of the transfer orbit. So, the semi major axis x was given by r initial, plus r final divided by 2. So, this was 2 plus 3.5 divided by 2 astronomical units, so there 2.75 astronomical unit. This we calculated last time. And then using various relationship then we worked out omega A also, so omega A turned out to be 7.0393902 into 10 to the power minus 8 radian per second. And omega B similarly, we calculated to be 3.0407308 into 10 to the power minus 8 radian per second. Now, the time of flight, for completing this orbit from here to here, so this is half the orbit. So we will say, this is T_1 by 2. This is nothing, but pi times 2.75 astronomical unit. It is in astronomical unit, so this we write as R , so where R equal to 1 astronomical unit divided by μ and this whole cube under root.

So, this is the half time period and if we put 2π , means that will be time to a start from here to here for the satellite and come back again to this point. And putting the relevant values then we calculated to put the value for the R, so last time we have stated the value of R. So R was having a value of R equal to 1.49596×10^8 kilo meter, so this is one astronomical unit. And similarly, μ the value or the μ that we choose, it was 1.32715×10^{11} kilo meter cubic per second square. So with this values inserting into this, this gives you 7195639 seconds. And if you convert this into day, so in day this will turn out to be 832.82765 days. Now, divided by 71956309, and divide by 24 times 36100, so this will give you this value, this is 719.

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$$\Delta T_A = \frac{\Delta \theta_A}{\omega_A} = 337667308 \text{ seconds}$$

$$= 390.8253 \text{ days.}$$

$\Delta T_A \rightarrow$ is the waiting period before you can launch satellite from Asteroid "A" to have maximum Fuel Efficiency.

And then we also calculated $\Delta \theta_A$ by ω_A , which is equal to T_A , ΔT_A . so ΔT_A is nothing, but the time taken for the asteroid to move from this point to this point. And this is what was asked in the question that how much time is required, before the satellite can be launched from the asteroid A. So this is the time, this is the angle before you can launch, and if you divide by the angular rate of the asteroid, so that gives you the time, so this is what exactly has been done. So, this is the waiting period before you can launch the satellite. And this turned out to be 337667308 seconds, which was equal to 390.8253 days. So, this was the waiting period ΔT_A is the waiting period before you can launch satellite from asteroid A to have maximum fuel efficiency. So if you have to send your satellite from earth to mars, so you have to follow exactly the same pattern.

Here you need to know the initial position of the earth, initial position of the mars, at a particular epoch from where you are counting, and then you have to compute when your window is available for launching the satellite. So that window you have to calculate exactly in the same way, and then you can repair the mission for sending your satellite to mars. Now, by how much angle the asteroid A will move from this epoch. So this is our starting epoch, and from here how much angle it is a going to describe. So the asteroid A is already here in this position, it is moving to this position, and then it is launching the satellite. So in the meanwhile asteroid A will move from position A to suppose, it is moving and reaching this position A prime, while the satellite catches up at B prime, so asteroid has moved to A prime, which is the position given here.

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$$\theta'_A = \theta_A + \Delta\theta_A + \frac{\pi}{\sqrt{\mu}} (2.75 R)^{3/2} \times \omega_A$$

$$\Delta\theta_A = \omega_A \times \Delta T_A = 7.0393902 \times 10^{-8} \times 33767308$$

$$= 2.3770126 \text{ rad.}$$

$$\frac{\pi}{\sqrt{\mu}} (2.75 R)^{3/2} \omega_A = 7.0393902 \times 10^{-8} \times 71956309$$

$$= 5.0652845 \text{ rad.}$$

Annotations: 28-10, © CET I.I.T. RGP, Gravitation Independent of Sun, 1A.U.

So, A prime will be the delta theta A prime, this will be equal to theta A plus delta theta A plus. So, you have the theta A from here to here, and this is the angle delta theta A, and the rest of the angle from here to here, here to this place. Now, this depends on the angular velocity of the asteroid. And the time taken in the meanwhile how much time the satellite takes from here to here. In the meanwhile, asteroid B is reaching from this place to this place, and that will be given by the half period of the elliptical orbit. So, this is 2.57 times R to the power 3 by 2 times omega A. Now insert the values for all of them and you can calculate. So delta theta A we have already found out, delta theta A was. We can write it here, omega A times delta T A. so delta T A is the time that we have just now calculated. This is the quantity here delta T A 390 and second it is a given like this, and

delta theta A also was available to us. Anyway we will write here, this is omega A is 7.0393902 into 10 to the power of minus 8 times.

This is the angular velocity and times delta T, so delta T is your delta T A, this is 33767308 this is in seconds, this is what the quantity is shown. So we have taken here in this place, so this turns out to be 2.3770126 radian. Similarly, this quantity you can compute and this quantity pi by mu under root, times 2.75 r to the power 3 by 2 times omega A. Inserting all the values R is the 1 astronomical unit, and omega is the angular speed which is shown here. So inserting this value pi you know, and mu earlier we have stated. This is the gravitation constant of sun. This is not the universal gravitation constant; this is the gravitational constant of sun, as in earlier lecture we have discussed. So, by inserting all the values, this will turn out to be. So, omega A is 7.0393902 into 10 to the power minus 8 and this quantity we can compute and write here. So, this quantity is 71956309, you can verify yourself, so this will turn out to be 5.0652845 radian.

(Refer Slide Time: 38:21)

28-11

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$$\theta'_A = 139^\circ + (2.3770126 + 5.0652845) \times \frac{180}{\pi}$$

$$\theta'_A = 139^\circ + 426.41227^\circ = 565.41227^\circ$$

New Position of the Asteroid B $\rightarrow B'$

$$\theta'_B = \theta_B + \omega_B \Delta T_A + \omega_B \times \frac{\pi}{\sqrt{\mu}} (2.75 R)^{3/2}$$

$$\omega_B \Delta T_A = \frac{3.0407308 \times 10^{-8}}{\omega_B} \times \frac{33767308}{\Delta T_A}$$

$$= 1.0267729 \text{ rad.}$$

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So therefore, theta prime A in degree this will be given by 139 degree plus, 2.3770126 plus 5.062845 into 180 divided by pi, so 139 degree plus 426.41227. Each of the competition you must verify yourself if you want to learn. And this is 56.41227 degree this is what is coming, so around 56.41 degree. Similarly, we have to calculate the position of the asteroid B. So new position of the asteroid B, which is B prime, so theta B prime; this will be theta B plus omega B times delta T A plus omega B times pi, where

102 mu 2.75R to the power 3 by 2. We can look what are the quantities these are. Look into this figure, so theta omega B times delta T A. So, this is the time in which the asteroid a moves from point A to A 1, this is the point A 1. So it is moving from this position to this position and that time we have written as delta T A, and this time we have earlier calculated this is known to us, omega B is known to us, this quantity is known to us, all this quantities are known. And it is basically your flight time of the satellite.

So the satellite the time it takes to move from here to here, so in the same time, so the time A takes to move to A1, so that time B will move from here to suppose, it moves to this place. And there after the satellite moves from here to here. So B will approach here in this point and both of them will meet together here in this point B prime, so this is what the equation appears. Now each of the values you can compute separately, so omega B times delta T A, I am against that you must do it independently by computing and verifying all the results, and that will give you confidence to work out this example. So this is your delta T A and this is omega B. So this will turn out to be 1.0267729 radian, this is the value. Now we next need to compute this, so this quantity earlier we have computed in the previous example in the previous step. Here we computed this quantity, which is appearing here in this place 71956309. So we can utilize here and this has to be multiplied by omega B.

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Handwritten mathematical derivation on a blue background. The derivation shows the calculation of θ'_B and θ'_A . The steps are as follows:

$$\omega_B \times T_{1/2} = \omega_B \left(\frac{\pi}{\sqrt{\mu}} (2.75R)^{3/2} \right) \left(T_{1/2} \right)$$

$$= 3.0407308 \times 10^{-8} \times 71956309$$

$$= 2.1879977 \text{ rad}$$

$$\theta'_B = 271^\circ + (1.0267729 + 2.1879977) \times \frac{180}{\pi}$$

$$= 271^\circ + 144.19278^\circ = 455.19278^\circ$$

At the bottom, the final results are circled in green:

$$\theta'_A = 565.41227^\circ$$

$$\theta'_B = 455.19278^\circ$$

An arrow points from the circled results to the text: "As known A is leading in latitude".

So next the quantity $w_B \times T_{1/2}$, this will be $\omega_B \times \pi \times \mu$ under root times 2.75 this is the semi major axis of the transfer orbit what we are writing here. And this is the period for completing the half orbit, so this is your $T_{1/2}$. Now, inserting this values $\omega_B = 30407308$ into 10 to the power minus 8. And this quantity we have calculated earlier, this is nothing, but 33, no in this, not the quantity. Here we have done it 71956309. So if you multiply this, this turns out to be 2.1879977 radian, and therefore θ'_B this can be written as 271 plus 1.0267729 plus 2.1879977 into 180 divided by π . So 271 degree plus 184 point 1.9278 degree, so this turns out to be 455 and 19278 degree means point 192 degree or point 193 degree we can have approximate. So this is your θ'_B . So what ultimately we have got as the result, θ'_A this is equal to 565.41227 degree and θ'_B equal to 455.19278 degree. Therefore, you can see from this place that, asteroid A is leading a latitude.

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28-13

$$\theta'_A - \theta'_B = \Delta\theta = 565.41227^\circ - 455.19278^\circ$$

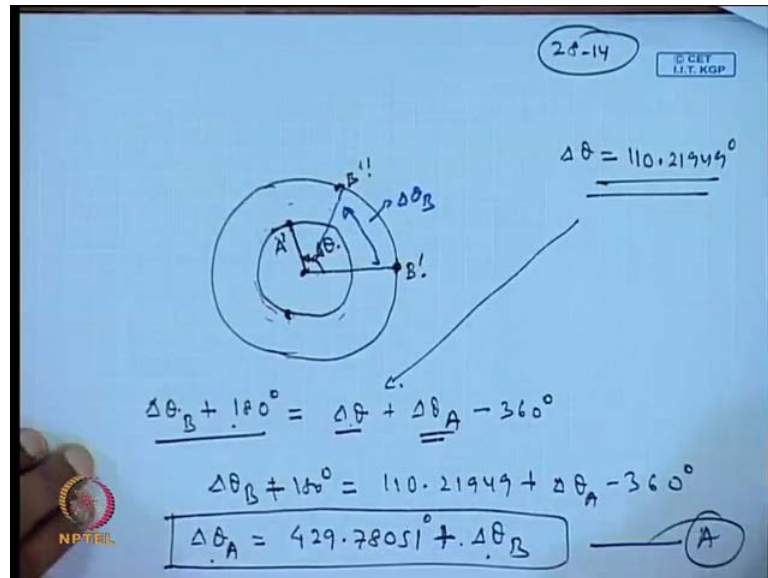
$$= 110.21949^\circ \checkmark$$

(b) Q. If the satellite which has reached point B' has to return back to Asteroid A again then how long the wait period will be. for max fuel economy?

So this quantity θ'_A minus θ'_B , this will write subtract and write this as $\Delta\theta$, which will be 565.41227 degree minus 455.19278 degree, and this turns out to be 110.21949 degree. So this is the lead available to asteroid A. Now the part B of the question is part A is over. So part B of the question is that, once the asteroid has reached into the point B, and the satellite has got this rendezvous has taken place. So satellite has got the asteroid B at B' . Now if the astronomer who is sitting in the satellite, if he wants to return back to A again how long he has to wait? If he wants to minimize the fuel. Next question is; that if the satellite which has fixed point B' has

to return back to asteroid A again, then how long the wait period will be, for maximum fuel economy. So, this is the second part of the question.

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Again we draw the figure, so with respect to asteroid B we can show that this is the position B prime suppose. And the asteroid which is in a smaller orbit, so this is located somewhere in this point. So this is your A prime point, so this is the initial situation. And the lead is of the lead angle we will show it by delta theta and delta theta just now we calculated, it turned out to be 110.21949 degree. So, how long the waiting period will be before we can launch a satellite from the asteroid which is now at prime B prime. So suppose that, before the launch can be done, so this moves to some new position here B double prime. In the mean while it will move into A prime will also move. So A prime is moving this asteroid A is also moving asteroid is also moving, but the thing is that we have to always launch in such a way. Now appear this will be the apogee position and then you have to catch up this at the perigee position of this transfer orbit. So, we need to work out further this quantity.

Now, let us see how to do it, so we will write delta theta B plus 180 degree. We are writing in terms of degree, later on we will convert into radian. So you see that delta theta B this will be indicated by something like this line, where this is your angle delta theta B. And then suppose it catches A at this point, so this will be the angle from here to here. Now but, this satellite asteroid A is in the smaller orbit so its angular rate is

passed. So by the time it goes here, this will be covering a larger angle and it will cross it. So, it would not be possible to catch up here in this place, you will have to wait for one more period, once it returns back and comes into this position so we have to compute for that quantity. So, this will be given by delta theta plus say that delta theta A is the angle covered by the asteroid A.

So delta theta is already the lead available, and delta theta A is the another angle that it will be moving around, and coming into this position and then B will be coming and catching up here in, the satellite will start from here and catch up here in this position. So we need to subtract here 360 degree, because it has taken one round already hereto come to this point. So these things must be taken care off. If you write in this fashion then your delta theta B. Insert the value of delta theta from this place. So delta theta B can be written as, delta theta B plus 180 degree equal to delta theta 110.21949 plus delta theta A minus 360 degree, and working it out delta theta A can be written as 429.78051 degree, plus delta theta B. So this time we have expressed delta theta A in terms of delta theta B. So let us say this is our equation number A.

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$$\Delta\theta_A = 429.78051^\circ + \Delta\theta_B \quad \text{--- (A)}$$

$$\text{in rad.} \quad \Delta\theta_A = 429.78051 \times \frac{\pi}{180} + \Delta\theta_B \quad \text{rad.}$$

$$\Delta\theta_A = 7.501085 + \Delta\theta_B$$

$$\frac{\Delta\theta_A}{\omega_A} = \frac{\Delta\theta_B}{\omega_B} + \Delta T/2$$

flight time of the satellite

Now, the next step will be, to compute the time taken. So, to cover this angle the total time required and to cover this angle the total time required, they must be same. So, let us come convert this into the radian. So, if we convert this into radian, so delta theta A can be written as in radian 429.78051 degree into pi by 180 plus delta theta B, where

delta theta A and delta theta B are on now in radian. So, this becomes 7.501085 plus delta theta B. Now, we can go for calculating the equating the time, so now delta theta A divided by A will move from this place, and it will it goes once around this and whatever happens to this. So, we have the time delta theta A by omega A, this must be equal to delta T 1 by 2 is, is the flight period. So, we will continue with this, time is getting over. So we will complete in the next lecture. Thank you very much.