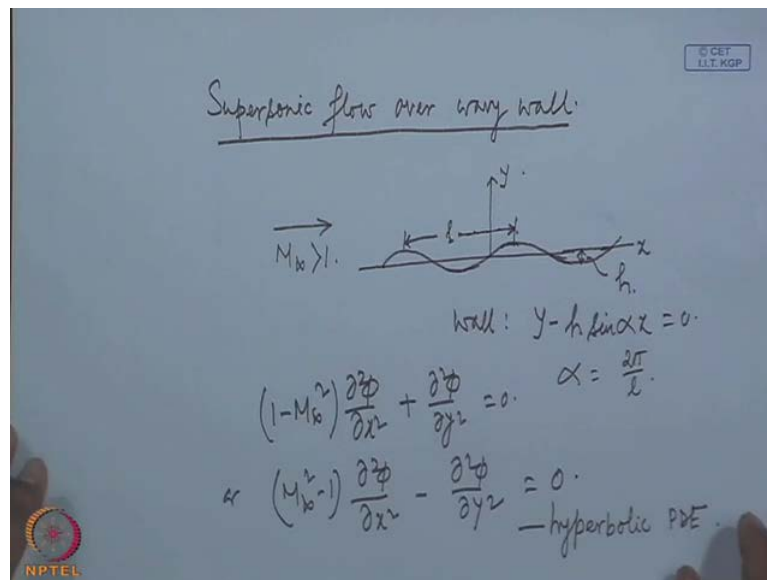


**High Speed Aero Dynamics**  
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**Lecture No. # 27**  
**Linearized Flow Problems (Contd.)**

So as **example** example of solution for linearized flow problems, we consider subsonic flow first wavy wall and the solution gave us few important observations and the most important of them, that you found the perturbation is maximum on the wall itself, and as we move away from the wall the perturbation decreases, there all then attenuation factor we also saw that the attenuation reduces as Mach number increases. Now, we will consider this same example in Supersonic flow, that is a Supersonic flow past or wave shift wall.

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So, this is what we will be discussing today, a Supersonic flow past wavy wall the problem is essentially the same that is, we have an wave shaped wall the amplitude once again is h and length of 1 wave is once again, l that is once again the wall is given by y minus h sin alpha x equal to 0, where alpha is 2 pi by l, the governing equation in this

case is once again  $1 - M_\infty^2$  or since,  $1 - M_\infty^2$  is negative. We write this as  $M_\infty^2 - 1$  and the equation becomes  $d^2\phi/dx^2 - 1/\beta^2 d^2\phi/dy^2 = 0$ .

As, we have mentioned earlier that this equation is hyperbolic and of course, we do not need to specify boundary condition in all boundary, which is the property of hyperbolic partial differential equation and also they represent of propagation problem.

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$M_\infty^2 - 1 = \beta^2$   
 $\Rightarrow \frac{\partial^2 \phi}{\partial x^2} - \frac{1}{\beta^2} \frac{\partial^2 \phi}{\partial y^2} = 0$   
 — wave equation.  
 $\phi(x, y) = f(x - \beta y) + g(x + \beta y)$   
 We set,  $y = 0$ ,  
 Using wall boundary condition (linearized)  
 $\left(\frac{\partial \phi}{\partial y}\right)_{y=0} = -\beta \left[ f'(x - \beta y) \right]_{y=0}$   
 $f' = \frac{\partial f}{\partial (x - \beta y)}$

Now, this time we consider write  $M_\infty^2 - 1$  equal to  $\beta^2$ , please note the change in the sign of  $\beta^2$  in the subsonic case, we consider  $1 - M_\infty^2$  to be  $\beta^2$ , but now, we take  $M_\infty^2 - 1$  equal to  $\beta^2$  and then this equation becomes  $d^2\phi/dx^2 - 1/\beta^2 d^2\phi/dy^2 = 0$ . Once again, it must be remembered that  $\phi$  in this equation is perturbation potential; that is  $\phi$  is perturbation potential and its gradient gives the only the perturbation velocity, not the total velocity. So, for to find the total velocity pre stream velocity, must be added to this perturbation velocity which is gradient of  $\phi$ .

Now, this is familiar wave equation and we have very well known solution for this, which is  $\phi(x, y)$  is function of  $x - \beta y$  plus  $g$  into  $x + \beta y$ , the solution is quite well known.

Now, for the time being, we set  $g$  equal to 0 and we see while  $g$  chosen to be 0 in fact, it has something to do with the direction of the flow and which makes a distinction between upstream and downstream, which is again a property of the hyperbolic partial differential equation. Now, to find the explicit form of this function  $f$ , we consider the boundary condition, the boundary conditions are of course, the same as in case of subsonic flow, there is no change in boundary conditions using the wall boundary condition. **using the wall boundary condition**

Which says, that the slope of the streamline is same as the slope of the body at which is of course, linearized as before. Which gives that  $d\phi/dy$  at  $y$  equal to 0. We see, here that instead of evaluating the velocity component on the wall itself, we are evaluating at  $y$  equal to 0 that is the linearization or approximation, but consistent with the linearized contribution theory and this gives minus beta  $x$  prime  $x$  minus beta  $y$  at  $y$  equal to 0, remember that  $f$  prime is that is,  $f$  is differentiated with respect to its argument.

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$$\Rightarrow -\frac{U_{\infty} h}{\beta} \sin \alpha x = f(x).$$

$$\left[ \frac{\partial \phi}{\partial y} = U_{\infty} \alpha h \cos \alpha x \right]$$

Hence

$$\begin{aligned} \phi(x, y) &= f(x - \beta y) \\ &= -\frac{U_{\infty} h}{\beta} \sin \alpha (x - \beta y) \\ &= -\frac{U_{\infty} h}{\beta} \sin \alpha (x - \sqrt{M_{\infty}^2 - 1} y) \end{aligned}$$

$$u = -\frac{U_{\infty} \alpha h}{\beta} \cos \alpha (x - \beta y)$$

$$v = U_{\infty} \alpha h \cos \alpha (x - \beta y)$$

Now,  $d\phi/dy$  at  $y$  equal to 0 which, we have already seen is minus  $u_{\infty} h$  by beta  $\sin \alpha x$  equal to this is what, we get substituting  $d\phi/dy$  at  $y$  equal to 0 whereas, before  $d\phi/dy$ . ((no audio 09:59 to 10:32))

So, this is the function explicit form of the function  $f$  and hence or potential becomes perturbation potential is  $y$   $x$   $y$  equal to function of  $x$  minus beta  $y$ . Which is or in terms of mach number, this can be written as  $\sin \alpha x$  minus root over  $m$  infinity square minus

1 into y the perturbation velocity components are  $d\phi/dx$  that makes, infinity  $\alpha h$  by  $\beta \cos$  of  $\alpha$  into  $x$  minus  $\beta y$ ,  $u$  infinity  $\alpha h \cos$  of  $\alpha$  into  $x$  minus  $\beta y$ .

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The image shows a handwritten derivation of the linearized pressure coefficient  $C_p$  and a note about exponential attenuation. The derivation starts with  $C_p = -2 \frac{u}{U_\infty}$  and is transformed into  $C_p = \frac{2\alpha h}{\beta} \cos(\alpha x - \beta y)$ . This is then expressed in terms of the Mach number  $M_\infty$  as  $C_p = \frac{2\alpha h}{\sqrt{M_\infty^2 - 1}} \cos(\alpha x - \sqrt{M_\infty^2 - 1} y)$ . Below the derivation, a note states: "1. No exponential attenuation factor in  $u, v$  or  $C_p$ . Perturbation remains unchanged if  $x - \beta y = \text{constant}$ . Constant perturbation along the lines  $x - \beta y = \text{constant}$ ".

And the linearized pressure coefficient is minus 2  $u$  by  $u$  infinity that gives 2  $\alpha h$  by  $\beta \cos$  of  $\alpha x$  minus  $\beta y$  or in terms of Mach number. It is root over  $m$  infinity square minus 1 for  $\alpha x$  minus root over  $m$  infinity square minus 1  $y$ .

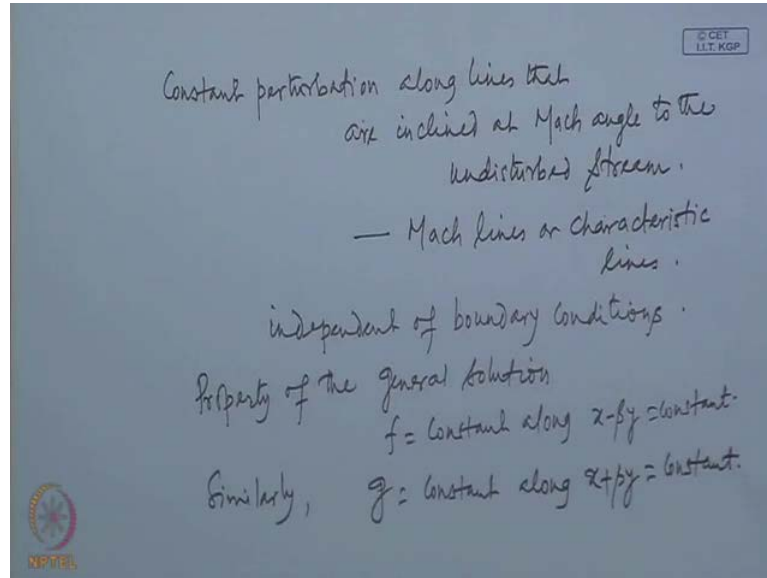
So, this is the linearized pressure coefficient and what we see here, that we did not need to satisfy any boundary condition at infinity to obtain, this solution that is again as a special property of hyperbolic partial differential equation that, we do not need to satisfy the boundary condition at all boundaries. Now, look into this perturbation velocity and pressure coefficient what immediate, we can see is that there is no exponential attenuation factor here.

So, the first observation that we can make is no exponential attenuation factor in  $u, v$  or  $C_p$  and it simply means that the perturbations do not vanish. As, we increase our  $y$  which is unlike subsonic case however, we saw that the perturbation decreases as  $y$  is increased in this case you see that of course, the highest perturbation is obviously still on the wall, but it is not decreasing with increasing distance, meaning that in a supersonic flow the perturbation will not vanish. Even at very far distance; very far off from the body. So, supersonic perturbation will not vanish even at very great distance from the

body. In fact, what we can see here that the perturbation remains constant **perturbation remain constant** as long as this remain constant.

So, now  $x - \beta y = \text{constant}$  is essentially, as straight line in the  $x - y$  plane. So, the perturbation is constant along **along** the lines  $x - \beta y = \text{constant}$ .

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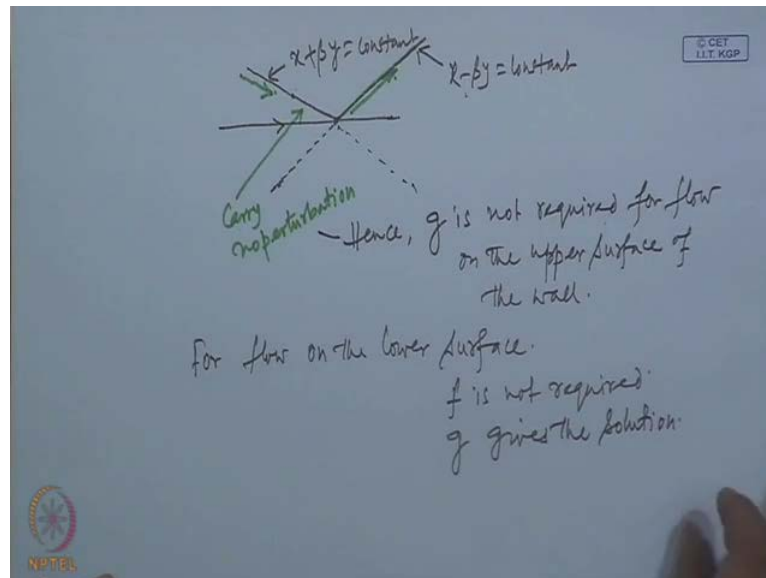


And obviously, these lines make an angle  $\beta$  **or we say that** or we can say that the constant perturbation along lines that are inclined at Mach angle to the undisturbed stream. That is, along any line which makes Mach angle with respect to the undisturbed stream the perturbation remains constant, even up to infinity or in practical case to a very large distance. Now, the lines which makes Mach angle with the **with** respect to the undisturbed stream are called as before, we have called them the Mach lines. These are the Mach lines or the characteristic lines.

So, the perturbations remain constant along the Mach lines or the characteristics lines. Now, once again we see that this has nothing to do with the boundary conditions and in fact, this is the property of the basic solution itself. So, this is independent of the boundary conditions **this fact is independent of boundary conditions independent of boundary conditions** or whether that the **flow** flow is such that it is perturbation remain constant along Mach lines irrespective of whatever, body shape, we are considering in a supersonic flow. So, **this is** this property is contained within the specific solution,  $f = \text{constant along } x - \beta y = \text{constant}$ .

So, property of the solution itself **property** of the general solution,  $f$  equal to constant along  $x$  minus  $\beta y$  equal to constant and **similarly**, similarly, we can see  $g$  equal to constant along  $x$  plus  $\beta y$  equal to constant.

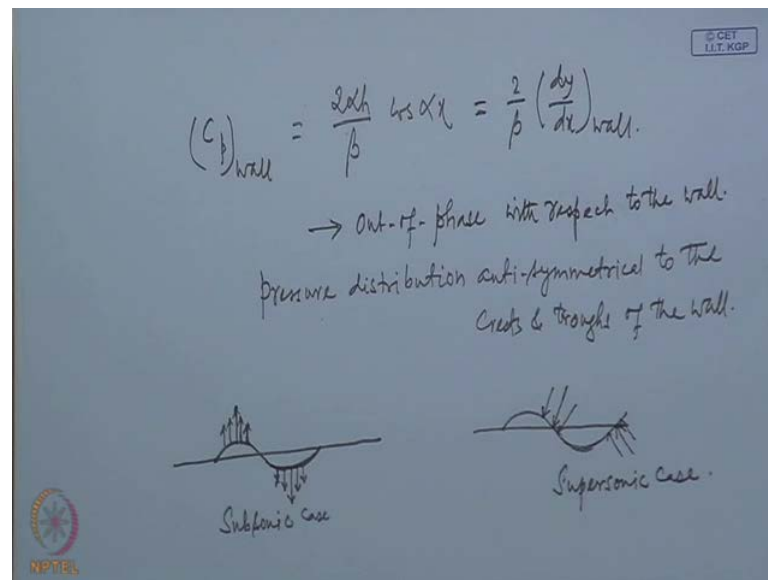
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As, we can see that with respect to any wall or any streamline. Now, these set of characteristics are as you can see inclined downstream and meaning that, they are originating from this wall **they are originating from the wall** and they carry the information from the wall to the **field** flow field, while the other set of characteristics. Which are inclined upstream, meaning that they bring in information from infinity and hence, they carry no perturbation.

So, carry no perturbation this set originates at infinity and brings in perturbation to the wall. However since, there is no **perturbation** the perturbation is not created on the wall it at the infinity. So, these are carrying no perturbation, while this originates at the wall and carries perturbation to the field. So, this is the reason that for flow over the wall only the function  $f$  is important hence,  $g$  is not required for flow on the upper surface of the wall. However if, we consider the flow on the lower surface, then this is what is originating at the wall and carrying the perturbation to the field. While this then is originating at infinity and there is no perturbation. So, for the lower **flow** for flow on the lower surface  $g$  gives the solution.

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Now, let us see that  $C_p$  on the wall, the pressure coefficient on the wall  $2\alpha h$  by  $\beta \cos \alpha x$  which can be written as  $2$  by  $\beta \frac{dy}{dx}$  wall, and if you remember, this is the same pressure coefficient that, we obtained in case of weak wave theory or linearized shock expansion theory. So, we get the same result here also, one more thing that, this is now, anti phase to the wall out of phase with respect to the wall. Maxima are maxima and minima are shifted by a phase of  $\pi$  by  $2$  with respect to the maxima and minima of the wall.

So, we have pressure distribution **antiphased pressure distribution** anti symmetrical to the crests and troughs of the wall, ((no audio 27:33 to 28:30)) remember the pressure is these are of course normal reduction for the supersonic case however, this as ((no audio 28:42 to 29:38)) and this of course, clearly, shows that for if the wall is symmetric. As, we have considered, there will be no lift in both the cases. However, in this case there will be drag force acting, while there is no drag force here.

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Handwritten derivation on a whiteboard:

Drag per wave length:

$$G_D = \frac{1}{l} \int_0^l C_p \left( \frac{dy}{dx} \right)_{wall} dx.$$

Side note:  $C_p \sin \theta \approx C_p \theta = C_p \left( \frac{dy}{dx} \right)_{wall}$

$$= \frac{1}{l} \int_0^l \frac{2}{\beta} \left( \frac{dy}{dx} \right)_{wall}^2 dx.$$

$$= \frac{2}{\sqrt{M_\infty^2 - 1}} \overline{\left( \frac{dy}{dx} \right)_{wall}^2} \left( \frac{dy}{dx} \right)_{wall}^2 = \frac{1}{l} \int_0^l \left( \frac{dy}{dx} \right)_{wall}^2 dx.$$

— wave drag

Now the magnitude of the drag force per wavelength can be written as  $C_D$  equal to 1 by  $l$  0 to  $l$  this gives the component along the flow direction component of the pressure coefficient along the flow direction which is say  $C_p \sin \theta$  is nearly equal to  $C_p \theta$  that is  $C_p d$  by  $dx$  of course, this  $dy$   $dx$  of wall.

Now, as we have already seen that the  $C_p$  is written as  $2$  by  $\beta$  into  $dy$   $dx$ . So, this becomes  $dy$   $dx$  square  $dx$  and this, we can replace by a average or this average is defined. So, once again we have seen that this, there is a drag in viscid two dimensional supersonic flow, which is called the wave drag, because of the wave nature of the solution of supersonic flow again considering the range of validity.



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Range of applicability

1. Coefficient of  $\frac{\partial^2 \phi}{\partial x^2}$  on LHS  $\gg$  Coefficient of  $\frac{\partial^2 \phi}{\partial x^2}$  on RHS

or  $M_{\infty}^2 - 1 \gg M_{\infty}^2 (\gamma + 1) \left( \frac{h}{U_{\infty}} \right)_{\max}$

or  $M_{\infty}^2 - 1 \gg \frac{M_{\infty}^2 (\gamma + 1) \alpha h}{\sqrt{M_{\infty}^2 - 1}}$

or  $\frac{M_{\infty}^2 (\gamma + 1) \alpha h}{(M_{\infty}^2 - 1)^{3/2}} \ll 1$

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As, before we can see since first of all we have considered the linearized supersonic flow or there is supersonic flows. Which can be linearized and this implies that, the coefficient of  $\frac{\partial^2 \phi}{\partial x^2}$  on the left hand side **the coefficient of  $\frac{\partial^2 \phi}{\partial x^2}$  on left hand side** is much larger than coefficient of  $\frac{\partial^2 \phi}{\partial x^2}$  on right hand side. ((no audio 34:43 to 35:15)).

Now,  $u$  by  $U$  infinity maximum as, we have already seen is  $\alpha h$  by  $\beta$ , ((no audio 35:29 to 36:08)) which again gives and we see that, we have again obtain the same relation. As, we have seen in case of a subsonic flow, that the linearization can be used only if, this condition is satisfied and if not as this quantity moves towards one, the applicable validity becomes 4 and when this reaches very close to 1. This approximation cannot be used and this terms on the right hand side, cannot be neglected meaning this, suggest when the flow will become transonic.

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Combining with the subsonic case

$$-1 < \frac{M_0^2(r+1)\alpha_h}{(1-M_0^2)^{3/2}} < 1.$$

Complete linearization is applicable outside the range.

Flow is transonic within the range,  
 $\alpha_h$  is related to the maximum slope of the body.

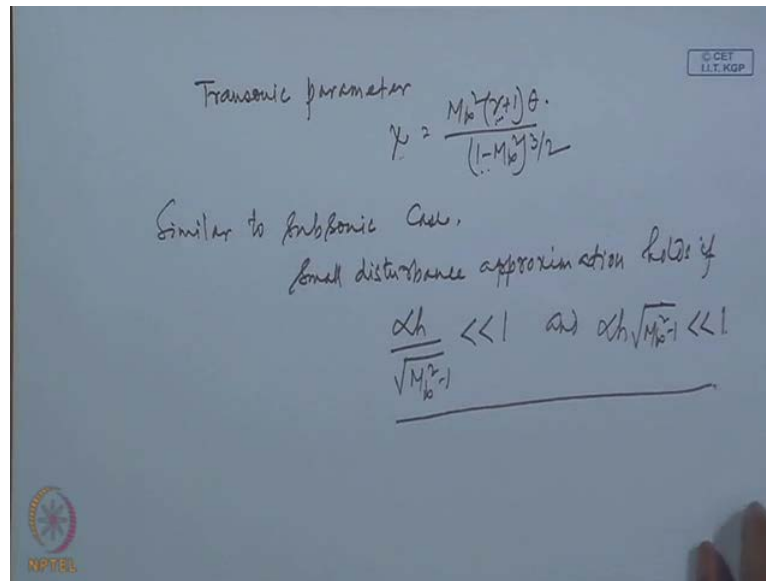
Definition of transonic flow

$$-1 < \frac{M_0^2(r+1)\theta}{(1-M_0^2)^{3/2}} < 1.$$

Now, if we combine with the subsonic case; combining the result with subsonic case. We have, ((no audio 38:00 to 38:32)) outside this range linearization is possible, complete linearization is applicable outside the range and the flow is transonic within the range, and as we have mentioned earlier or as you can see that  $\alpha_h$  the parameter,  $\alpha_h$  can be related to the maximum slope of the body. ((no audio 39:47 to 40:18))

So, we can replace this  $\alpha_h$  by the maximum slope, and this gives a concise definition of transonic flow. So, we can see **this is** this gives us a definition of transonic flow,  $\theta$  is the slope of the body then, and this term is usually called the transonic parameter it is denoted by  $\chi$ .

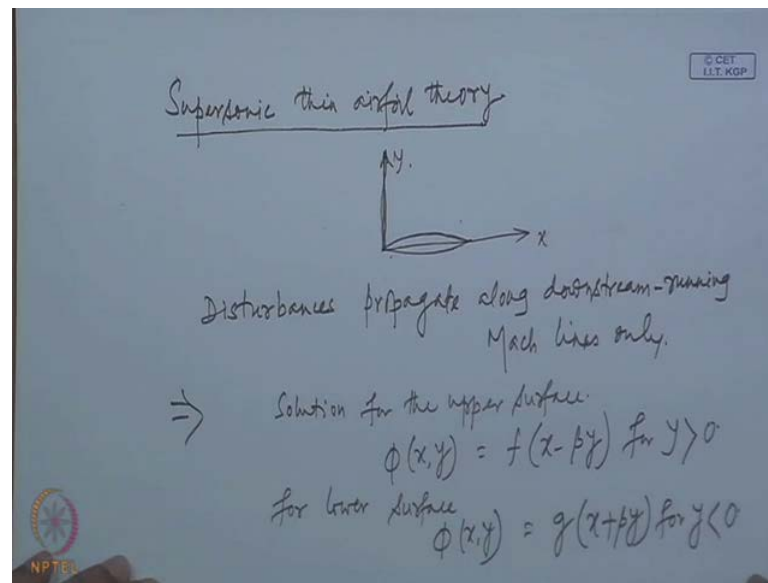
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So, we see that whether a particular flow can be called transonic or not depends on the free stream mach number and particularly and  $3/2$  exponent for the factor  $1 - M_{\infty}^2$  the slope of the body, and also the specific heat ratio  $\gamma$  that means, **it we** it depends on the gas itself. So, for a given body and given free stream Mach number the flow may not be transonic, if  $\gamma$  is **if gamma is** such that this condition is not satisfied.

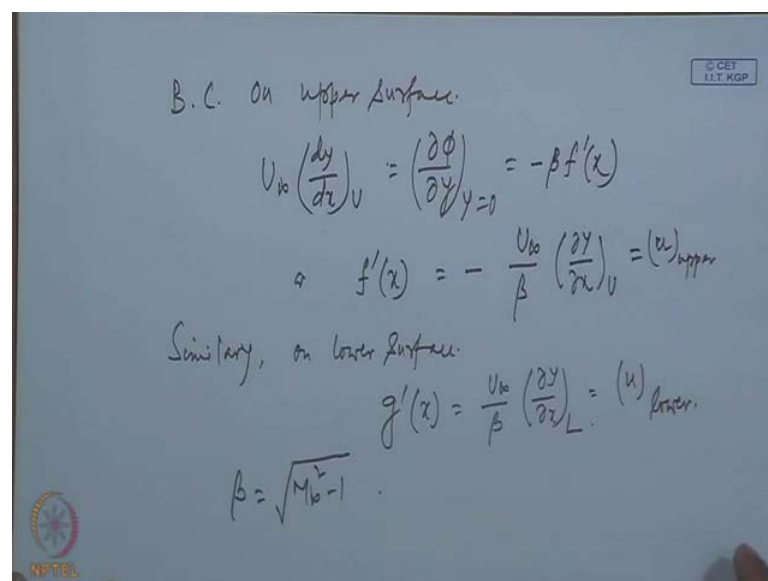
We can also see that the small perturbation, also leads the small perturbation; also leads to the earlier assumptions that, and similar to subsonic case small disturbance approximation. If  $\alpha h / \sqrt{M_{\infty}^2 - 1} \ll 1$ , and  $\alpha h \sqrt{M_{\infty}^2 - 1} \ll 1$ . This also you can see as before using the same approach that is  $u$  by  $U_{\infty}$  and  $v$  by  $b_{\infty} M v$  by  $U_{\infty}$  of much smaller than 1 to get this relation and the higher order term in the wall boundary conditions is negligible, if this is satisfied. So, hence these are the requirement for the small disturbance approximation to be valid.

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Now, with this we can find what is a supersonic thin airfoil theory, this will give us supersonic thin airfoil theory ((no audio 44:42 to 45:22)) from the solution, our way will we, have seen that disturbance propagated along downstream running Mach lines, only disturbances propagate along downstream running Mach lines only hence, the solution for the **solution for the** upper surface,  $\phi(x, y)$  equal to function of  $x$  minus  $\beta y$  for  $y$  greater than 0, for lower surface. Now, the specific form of  $f$  and  $g$  can only be obtained by satisfying the wall boundary condition.

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And boundary condition on upper surface gives us  $U \infty \frac{dy}{dx}$  on the upper surface is again approximated to  $d\phi/dy$  at  $y$  equal to 0, and which is  $d\phi/dy$  is minus beta a prime x or  $f$  prime x is minus  $U \infty$  by beta  $dy/dx$  on the upper surface. Similarly, on the lower surface and once, this must be remembered that beta in this case is root over  $M \infty^2 - 1$ . These are also the velocity component on the wall that is  $u$  on upper wall.

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The image shows handwritten mathematical derivations for the pressure coefficient  $C_p$  on the upper and lower surfaces of an airfoil. The equations are as follows:

$$C_p = -\frac{2}{U_\infty} f'(x) \quad \text{— upper surface}$$

$$-\frac{2}{U_\infty} g'(x) \quad \text{— lower surface.}$$

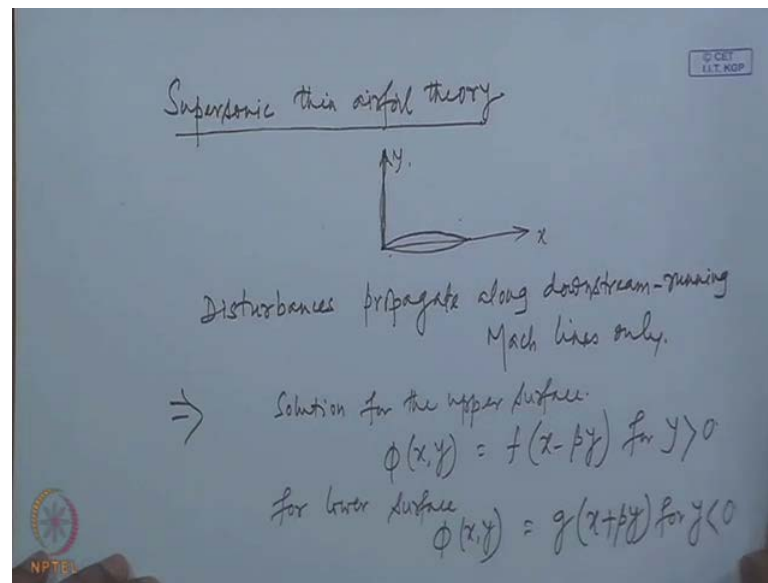
$$\Rightarrow C_{p_U} = \frac{2}{\sqrt{M_\infty^2 - 1}} \left( \frac{dy}{dx} \right)_U, \quad C_{p_L} = \frac{2}{\sqrt{M_\infty^2 - 1}} \left( -\frac{dy}{dx} \right)_L.$$

$C_p$  related to local surface slope.

And similarly, this is  $U$  on lower wall hence the pressure coefficient can be written as minus 2 by,  $U \infty f$  prime x on the upper surface and minus 2 by  $U \infty g$  prime x on the lower surface.

Now, substituting here a prime and  $g$  prime, this is this gives  $C_p$  on the upper surface as 2 by and on the lower surface. So, see the pressure coefficient on the airfoil surface is quite easily obtained from the solution of the wave shift wall or using the linearized problem of course, and we can see that, this leads to a local inclination theory, that  $C_p$  at any point on the surface is simply, related to it is slope surface slope at that point. So,  $C_p$  related to local surface slope;  $C_p$  at any point on the surface of their foil. Simply, depends on the slope at that point and of course, the free stream mach number within the frame work of thin airfoil or linearize theory.

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So, to summarize what, we have done today is solved linearized supersonic flow first wave view shift wall, and the most important thing that, we have observed that there is no exponential attenuation factor in case of a supersonic flow, that is the perturbation in a supersonic flow extends to far away theoretically. It infinity and the perturbation remain constant along the characteristic lines also, we have seen that **that** the disturbances propagate, along only downstream running Mach lines hence, solution of the **solution for the** over the upon however the flow the only function equal in the functionate and surface the solution that is required is the function  $g$ , considering the validity of this linearized approximation.

We have come to an explicit definition of transonic flow and we have defined a transonic parameter. Which, we have seen the depends the free stream mach number in particular to the prandtl glauert factor, we rise to the exponent  $3/2$ , it also depends on the slope of the geometry, but surprisingly. It depends on the gas itself, whether a flow at a particular mach number, over a particular geometry is transonic or not depends also on the gas itself also, we have seen that as before, we have found a drag force acting, even in two dimensional on in viscid flow over **over** a body.

So, we have confirm the fact again that, if Supersonic flow. There is a drag even, if the flow is in viscid two dimensional the drag, which we called wave drag and in this case also every valuated the wave drag then finally, we have explain extend this solution of

flow over a wavy wall to flow over a thin airfoil and we have developed what is known as the supersonic thin airfoil theory. Where, we have seen that the pressure coefficient at any point on the airfoil surface depends only on the local slope and which also depends on the free stream Mach number.

So, with this we conclude our definition that, this thin airfoil theory within the framework of small perturbation theory leads, us to a very useful, but very simple result for flow past on a foil and of course. As you can see that this solution will, we also applicable two or three dimensional geometry except near the t or the effect of three dimensionality will come in.