

Introduction to Finite Volume Methods-II
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Lecture – 26
Temporal Discretisation - II

So, welcome back to the lecture series of Finite Volume and where will continue our discussion where we left in the last lecture. Now, what happens to the transient diffusion case; now, that is the case where we had a convection case.

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Unsteady discretization

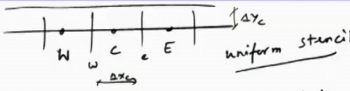
Transient diffusion

$$a_c^t \neq a_c^{t-\Delta t}$$

$$a_c^t = \frac{\rho_c \Delta y_c}{\delta x_e} + \frac{\rho_w \Delta y_c}{\delta x_w}$$

$$a_c^t + a_c^{t-\Delta t} \leq 0 \Rightarrow \frac{\rho_c \Delta y_c}{\delta x_e} + \frac{\rho_w \Delta y_c}{\delta x_w} - \frac{\rho_c^{t-\Delta t} \Delta x_c \Delta y_c}{\Delta t} \leq 0$$

$$\rho_c = \rho_w = \rho$$



$$a_c^{t-\Delta t} = - \frac{\rho_c^{t-\Delta t} V_c}{\Delta t} = - \frac{\rho_c^{t-\Delta t} \Delta x_c \Delta y_c}{\Delta t}$$

$$\Delta t \leq \frac{\rho_c^{t-\Delta t} \Delta x_c}{\left(\frac{\rho_c}{\delta x_e} + \frac{\rho_w}{\delta x_w} \right)}$$

$$\Delta t \leq \frac{\rho_c^{t-\Delta t} (\Delta x_c)^2}{2 \rho_c}$$

$$CFL^D = \frac{\rho_c \Delta t}{\rho_c^{t-\Delta t} (\Delta x_c)^2} \leq \frac{1}{2}$$

Now, we look at Transient diffusion problem. So, transient diffusion problem for this purpose is again you consider that one-dimensional stencil. So, C, E W; this is small e small w delta x C and if the cell height is there that would delta Y C, so, it is a uniform. Again, it is a uniform stencil. So, once you consider that uniform stencil, now the discretized equation for the transient diffusion term is going to be a C and these are the coefficients in there. So, the a C at present time level is given by gamma e delta Y C by delta x C plus gamma W delta Y C by.

Similarly, at the previous time level, this is minus rho C t minus delta C V C by delta t which is minus rho C t minus delta t del x C del Y C divided by del t. So, the CFL criteria says a C at t plus a C at t minus delta t, they less than 0 which will get you gamma e delta Y C by del x C plus gamma w del Y C by del x w minus rho C t minus

$\Delta t \leq \frac{\rho C \Delta x \Delta y}{\gamma_e}$. So, which will give you an criteria where Δt is less than $\rho C \Delta x \Delta y$ divided by γ_e . So, in case you have as we assume the uniform grid and let us say γ_e is same which is γ ; then, this Δt becomes $\rho C \Delta x \Delta y$ divided by 2γ .

So, that is the restriction you get transient diffusion problem. So, the CFL criteria for diffusion problem is $\gamma C \Delta x \Delta y$ by $\rho C \Delta x \Delta y$ and it has to be less than half for stability. So, you see individually when you look at the convection problem and the diffusion problem, the stability limits are different and when we combine them. So, the complete unsteady convection diffusion system. So, that is the one which you would like to take up next.

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Unsteady discretization

Transient C-D case

$$a_c^{t+\Delta t} = - \rho_c^{t+\Delta t} V_c \frac{\Delta t}{\Delta t}$$

$$a_c^t = \sum_{f \in \text{NB}(c)} \left(\Gamma_f \frac{E_f}{d_{cf}} + \|m_f, 0\| \right)$$

$$a_c^t + a_c^{t+\Delta t} \leq 0$$

$$\sum_{f \in \text{NB}(c)} \left(\Gamma_f \frac{E_f}{d_{cf}} + \|m_f, 0\| \right) - \rho_c^{t+\Delta t} V_c \leq 0$$

$$\Delta t \leq \frac{\rho_c^{t+\Delta t} V_c}{\sum_{f \in \text{NB}(c)} \left(\Gamma_f \frac{E_f}{d_{cf}} + \|m_f, 0\| \right)} \Rightarrow 1D, \Delta x, p, \Gamma$$

for diffusion case

$$\Delta t \leq \frac{\rho_c^{t+\Delta t} \Delta x_c \Delta y_c}{\sum_{f \in \text{NB}(c)} \left(\Gamma_f \frac{E_f}{d_{cf}} + \|m_f, 0\| \right)}$$

unstructured grid

$\Delta t \leq \frac{\Delta x_c}{u_c}$

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So, transient convection diffusion problem; so now, how one can go about it; let us consider this stencil which is in essentially unstructured grid.

So, when we are in the unstructured grid, then we have a cell connected with neighboring elements which are their faces like this and they are connecting with the. Now, here this is a transient convection diffusion problem or case where your coefficients at the from the matrix these are minus $\rho C V C$ by Δt a C at current instance is $f \text{ NB over } C$ $\gamma f E f$ by d_{CF} plus $m \cdot f$. Now, once we substitute this for the stability criteria which is essentially the criteria of $a C t$ plus $a C t$ minus Δt less than 0, we get

summation over $F \nabla C \gamma_f E_f$ by $dCF + m \dot{f}_0$ minus $\rho C t$ minus $\Delta t V C$ by Δt less than 0.

So, which leads to the following condition, the Δt must be $\rho C t$ minus $\Delta t V C$ divided by summation $F \nabla C \gamma_f E_f dCF + m \dot{f}_0$. So, that is the criteria one can get for both convection diffusion system; now, this equation the general requirement for the stability of explicit scheme. Now, the condition obtained earlier for pure convection or diffusion is in one dimensional system and the those could be the special case of this multidimensional problem. Now, again for the case of 1 dimensional diffusion with uniform grid with from here let us say from here one can derive those 1 dimensional case with uniform grid of Δx , density is constant ρ uniform diffusion coefficients γ ; then, one reduces this criteria for the for diffusion case.

Unsteady diffusion case that Δt less than equals to ρC which is t minus Δt . This $\Delta x \Delta Y C$ divided by summation of $F \nabla C$ which is now one can write this is γ_f which will be now E_f by $dCF + m \dot{f}_0$. Now, this guy is 0; this guy is essentially lead to $\Delta Y C$ by $\Delta x C$ and γ_f is γ_e plus γ_w . Now so, if the flow moves from left to right, this Δt criteria becomes $\Delta x C$ by $u C$ that is for convection. So, one case you can find out pure diffusion; other case you can find out pure convection.

So, the stability constant which is quite stringent and very restrictive as it forces the use of extremely small cell size and the grid size in the explicit transient formulation. So, when we look at the implicit transient formulation in the latter half of the lecture, we can see that restrictions actually gets relaxed quite a bit. Now, in system with backward Euler.

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Unsteady discretization

Backward Euler scheme

$$\phi(t) = \phi(t) - \phi(t-\Delta t) + \frac{\partial \phi}{\partial t} \Delta t - \frac{\partial^2 \phi}{\partial t^2} \frac{\Delta t^2}{2!} + \dots$$

• → current time level transient term.

$$\frac{(\rho_c \phi_c)^t - (\rho_c \phi_c)^{t-\Delta t}}{\Delta t} + L(\phi_c^t) = 0$$

$$(a_c^t + a_c^t) \phi_c + \sum_{F \in \text{NB}(c)} a_F \phi_F = b_c + a_c^{t-\Delta t} \phi_c^{t-\Delta t}$$

$$a_c^t = \frac{\rho_c^t \cdot V_c}{\Delta t}, \quad a_c^{t-\Delta t} = - \frac{\rho_c^{t-\Delta t} V_c}{\Delta t}$$

independent of Δt ; it is a stable scheme

$a_c^t, a_c^{t-\Delta t}$

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Backward Euler is sort of a implicit scheme. Now again what we can write our any variable t minus Δt is written as t minus Δt plus $\frac{\partial^2 \phi}{\partial t^2} \frac{\Delta t^2}{2}$ and so on. So, we can find out the first derivative of these like $\phi(t) - \phi(t - \Delta t)$ divided by Δt which is essentially $\frac{\partial \phi}{\partial t} \Delta t$.

Now, this one can replace in the discretised equations and that it will be like $\rho C \phi(t) - \rho C \phi(t - \Delta t) + L(\phi(t)) = 0$. Now, once we invoke this algebraic relations of the spatial operator and then, complete algebraic transient equation would be this is a C and then a C at the present location, I mean present time step plus $\phi(t)$. So, this one can define this dot which will represent the transient term at the current time level. So, this is the current time level transient term.

Since, we are using same coefficients a_C for the space and the time, we will just make it separate like that. So, $\text{NB}(C) a_F \phi_F - b_C + a_C^{t-\Delta t} \phi_C^{t-\Delta t}$; where, the coefficients for the transient term is $\rho C V_C$ divided by Δt and a_C^t is $\rho C V_C$ by Δt term. So, that is how we can actually get and you can use the field operator to get the ϕ . Now here, that at the time level t and the time level $t - \Delta t$ are also of opposite sign which guarantees that ϕ_C is bounded by this spatial neighbors at the current time step t and C is temporal neighbors from the previous time step $t - \Delta t$.

So, this implies the scheme is stable independent of the time step used. So, this is what the advantage of backward Euler, it is independent of delta t; it is a stable scheme. So, that is the important message. Now, one can actually I mean this is not an ideal scheme as it is also low order and solution obtained with the schemes are of the lower order of accuracy, unless very small time step that is like delta t is used.

So, which is also very restrictive condition because then your calculation would be marching at a slower space compared to; if you add up to a large time step for computational efficiency result would be very erroneous. So, there could be 1 more scheme which can be discussed which is called Crank Nicolson Scheme.

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Unsteady discretization

Crank-Nicolson Scheme (CN) : $\phi(t+\Delta t)$, $\phi(t-\Delta t)$, $\phi(t)$

$$\frac{\partial \phi(t)}{\partial t} = \frac{\phi(t+\Delta t) - \phi(t-\Delta t)}{2\Delta t} + O(\Delta t^2)$$

$$\frac{(\rho_c V_c)^{t+\Delta t} - (\rho_c V_c)^{t-\Delta t}}{2\Delta t} V_c + L(\phi_c^t) = 0$$

$$a_c^t \phi_c^t = b_c^t - \left(a_c^t \phi_c^{t-\Delta t} + \sum_{F \in \text{NB}(c)} a_F^t \phi_F^{t-\Delta t} \right) - a_c^{t-2\Delta t} \phi_c^{t-2\Delta t}$$

$$a_c^t = \frac{\rho_c^t V}{2\Delta t}, \quad a_c^{t-2\Delta t} = \frac{\rho_c^{t-2\Delta t} V}{2\Delta t}$$

$$\phi_c^{t-\Delta t} \approx \frac{\phi_c^t + \phi_c^{t-2\Delta t}}{2}$$

$$\begin{aligned} a_c^t \phi_c^t + 0.5 \left(a_c^t \phi_c^t + \sum_{F \in \text{NB}(c)} a_F^t \phi_F^t \right) &= b_c^t \\ -0.5 \left((a_c^t + 2a_c^{t-2\Delta t}) \phi_c^{t-2\Delta t} + \sum_{F \in \text{NB}(c)} a_F^t \phi_F^{t-2\Delta t} \right) & \end{aligned}$$

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So, the Crank Nicolson Scheme, Crank Nicolson Scheme what it uses it uses the information of t plus delta t; uses the information of t minus delta t and also at the level of t. So, it uses all these information. Now, using Taylor series expansion one can write $\frac{d\phi}{dt}$ is $\frac{\phi(t+\Delta t) - \phi(t-\Delta t)}{2\Delta t}$. This would be second order accurate now the since the order of accuracy and now if you substitute in the say equation this will give you $\rho_c V_c \frac{d\phi}{dt} + L(\phi_c) = 0$.

Then, once we invoke the spatial operator. So, we can write that complete system like a $C \phi = b$ minus $a \phi(t-\Delta t)$ plus $F \phi(t-\Delta t)$ minus $a \phi(t-2\Delta t)$ minus $2a \phi(t-2\Delta t)$. So, it uses the information at the current time

level previous time level and 1 level earlier, where a C this is rho C by 2 delta t a C t minus 2 delta t is rho C t minus 2 delta t V divided by 2 delta t. So, this scheme what it uses that at the t plus rho phi at t plus delta t which can be performed using the old values.

However, the old values are readed from the 2 levels before this one and accordingly it will modify the system. Now one more thing which is required that analysis of the stability of this particular scheme Crank Nicolson Scheme. So, this can be performed after slightly modifying the equation. In that case what modification is done is that which says phi at t minus delta t is approximated as phi t plus phi t minus 2 delta t divided by 2. Then, the complete algebraic equation this one brings down to a C phi C point 5 a C t phi C t plus summation of F NB C a phi F all at the tth level equals to b C t minus 0.5, where we write a C t plus 2 a C t minus 2 delta t phi C t minus 2 delta t plus NB C a F t phi F t minus 2 delta t.

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Unsteady discretization

$$a_c^t + 2a_c^{t-2\Delta t} \leq 0$$

1D: $\Rightarrow \Delta t \leq \frac{2\rho_c^{t-2\Delta t} V_c}{\dot{m}_i^{t-\Delta t}} = \frac{2\rho_c^{t-2\Delta t} \Delta x_c \Delta y_c}{\rho_c^{t-\Delta t} u_b^{t-\Delta t} \Delta y_c} \approx \frac{2\Delta x_c}{|u_c^{t-\Delta t}|}$

$CFL^c \leq 2$


Implementation details

Forward Euler $\rightarrow \frac{(\rho_c \varphi_c)^t - (\rho_c \varphi_c)^{t-\Delta t}}{\Delta t} V_c = -L(\varphi_c^t)$

Backward " $\rightarrow \frac{(\rho_c \varphi_c)^{t+\Delta t} - (\rho_c \varphi_c)^t}{\Delta t} V_c = -L(\varphi_c^t)$

+

CN $\rightarrow \left\{ \frac{(\rho_c \varphi_c)^{t+\Delta t} - (\rho_c \varphi_c)^{t-\Delta t}}{2\Delta t} V_c + L(\varphi_c^t) = 0 \right.$


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So, that is how you can get and the which becomes a C t plus 2 a C t minus 2 delta t less than equals to 0. Again if you go back to one dimensional system, then this equation provides you the criteria that delta t less than equals to 2 rho C t minus 2 delta V C by m dot e t minus delta t which is 2 rho C t minus delta t del x C del Y C divided by rho C t minus delta t u C t minus delta t delta Y C which is nothing but 2 delta x C by magnitude

of t minus Δt . So, which has been assumed that the advection term is discretised using the upwind scheme.

Now, using the CFL number for the convection defined by these expression, the criteria for the convection would be less than 2. So, larger the CFL limitation is very much helpful in the computing point of view, but the improved accuracy is just more important as it allows for accurate solution which can be achieved without the need to resolved to very small time step. So, specially that the second order derivative is now estimated from the error. So, now, we can see the accuracy security issues now.

Now, implementation if you look at these details. So, the implementation details because end of the day one has to think about from the programming point of view. Now what happens at the forward Euler where you get your $\rho C \phi C$ at t minus $\rho C \phi C$ t minus Δt by $\Delta t V C$ equals to minus $L \phi C$ t . Now, Backward Euler you get $\rho C \phi C$ t plus Δt minus $\rho C \phi C$ t divided by $\Delta t V C$ minus $L \phi C$ at t . Now if you add this two, Forward plus Backward Euler, what it does? It actually add these term and now, you add these term which will get you $\rho C \phi C$ t plus Δt . This guy gets cancelled minus $\rho C \phi C$ t minus Δt by $2 \Delta t$ into $V C$ plus $L \phi C$ t equals to 0 which is essentially Crank Nicolson Scheme.

So, this points to a simple implementation of the Crank Nicolson Scheme within a implicit scheme framework it is a 2 step procedure. So, in the first step 1 can do the back Euler formulation. So, to use implicitly find the value. So, this and the second step the value at time step t plus Δt can be found.

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Unsteady discretization

1st: Backward Euler - to find $(\rho\phi)^t$

$$(\rho\phi_c)^t + \frac{\Delta t}{V_c} L(\phi_c^t) = (\rho\phi_c)^{t-\Delta t}$$

2nd: $(t+\Delta t)$: $\frac{(\rho\phi_c)^{t+\Delta t} - (\rho\phi_c)^t}{\Delta t} V_c = -L(\phi_c^t) = \frac{(\rho\phi_c)^t - (\rho\phi_c)^{t-\Delta t}}{\Delta t} V_c$

$$\Rightarrow (\rho\phi_c)^{t+\Delta t} = 2(\rho\phi_c)^t - (\rho\phi_c)^{t-\Delta t}$$

$\Delta t \rightarrow$ divided into two equal steps ($\Delta t_{\text{local}} = \frac{\Delta t}{2}$)

CN — 2nd order accurate scheme.
 — Explicit scheme ← stability criteria / condition based on CFL like expression

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So, at the first step it is the Backward Euler which will get you to find $\rho\phi^t$ from $\rho\phi^t + \frac{\Delta t}{V_c} L(\phi^t) = \rho\phi^{t-\Delta t}$. Now the second step find the value at $t + \Delta t$ like $\rho\phi^{t+\Delta t} - \rho\phi^t$ divided by $\Delta t V_c$ minus $L(\phi^t)$ which is which will get you that $\rho\phi^{t+\Delta t} - \rho\phi^t$ minus Δt by $\Delta t V_c$.

So, that is $\rho\phi^{t+\Delta t} = 2\rho\phi^t - \rho\phi^{t-\Delta t}$. So, in these calculation one thing which is assumed as that Δt is divided into 2 equal steps which is $\Delta t_{\text{local}} = \frac{\Delta t}{2}$. Now, one can note here is that the Crank Nicolson Scheme is second order accurate scheme. So, it is an also still it is an explicit scheme, also it is an explicit scheme which has some stability criteria or condition based on CFL like expression. So, this also has the limit of the choosing Δt .

Like the Backward Euler or Forward Euler, they are very much restrictive using our CFL criteria, similarly Crank Nicolson also has certain restriction using CFL like criteria. But one thing which one can I mean note here since you achieve this calculation in 2 equal steps. So, which is essentially provides slightly better stable system compared to Backward Euler or Forward Euler. So, this is a and top of that it is a second order accurate scheme. So, one can note here that the Crank Nicolson is a better option

compared to Forward or Backward Euler and it provides higher order accuracy even in the temporal description and also stable and we look at other scheme in the next lecture.

Thank you.